

Solving simple quaternionic differential equations

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The renewed interest in investigating quaternionic quantum mechanics, in particular tunneling effects, and the recent results on quaternionic differential operators motivate the study of resolution methods for quaternionic differential equations. In this paper, by using the real matrix representation of left/right acting quaternionic operators, we prove existence and uniqueness for quaternionic initial value problems, discuss the reduction of order for quaternionic homogeneous differential equations and extend to the noncommutative case the method of variation of parameters. We also show that the standard Wronskian cannot uniquely be extended to the quaternionic case. Nevertheless, the *absolute value* of the complex Wronskian admits a *noncommutative* extension for quaternionic functions of one real variable. Linear dependence and independence of solutions of homogeneous (right) H-linear differential equations is then related to this *new* functional. Our discussion is, for simplicity, presented for quaternionic second order differential equations. This involves no loss of generality. Definitions and results can be readily extended to the n -order case. © 2003 American Institute of Physics.
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I. INTRODUCTION

Let \mathbb{R} , $\mathbb{C} \equiv \text{span}\{1, i\}$, and $\mathbb{H} \equiv \text{span}\{1, i, j, k\}$ be the real, complex, and quaternionic field,³

$$i^2 = j^2 = k^2 = ijk = -1$$

and

$$\mathcal{F}: \mathbb{R} \rightarrow \mathbb{R}$$

be the set of real functions of real variable. Through the paper, quaternionic functions of real variable, $\Psi(x) \in \mathbb{H} \otimes \mathcal{F}$, will be denoted by greek letters and constant quaternionic coefficients by Roman letters. To shorten notation the prime and double prime in the quaternionic functions shall, respectively, indicate the first and second derivative of quaternionic functions with respect to the real variable x ,

$$\Psi' := \frac{d\Psi}{dx} \quad \text{and} \quad \Psi'' := \frac{d^2\Psi}{dx^2}.$$

Due to the noncommutative nature of quaternions, it is convenient to distinguish between the left and right action of the quaternionic imaginary units i , j , and k by introducing the operators L_q and R_p whose action on quaternionic functions Ψ is given by

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$$L_q \Psi = q \Psi \quad \text{and} \quad R_p \Psi = \Psi p, \tag{1}$$

These (left/right acting) quaternionic operators satisfy

$$L_q L_p = L_{qp}, \quad R_q R_p = R_{pq}, \quad \text{and} \quad [L_q, R_p] = 0, \tag{2}$$

and admit for

$$q = q_0 + i q_1 + j q_2 + k q_3, \quad p = p_0 + i p_1 + j p_2 + k p_3, \quad \Psi = \Psi_0 + i \Psi_1 + j \Psi_2 + k \Psi_3,$$

the following *real* matrix representation⁴⁻⁶

$$L_q \leftrightarrow \begin{pmatrix} q_0 & -q_1 & -q_2 & -q_3 \\ q_1 & q_0 & -q_3 & q_2 \\ q_2 & q_3 & q_0 & -q_1 \\ q_3 & -q_2 & q_1 & q_0 \end{pmatrix}, \quad R_p \leftrightarrow \begin{pmatrix} p_0 & -p_1 & -p_2 & -p_3 \\ p_1 & p_0 & p_3 & -p_2 \\ p_2 & -p_3 & p_0 & p_1 \\ p_3 & p_2 & -p_1 & p_0 \end{pmatrix}, \quad \Psi \leftrightarrow \begin{bmatrix} \Psi_0 \\ \Psi_1 \\ \Psi_2 \\ \Psi_3 \end{bmatrix} \in \mathbb{R}^4 \otimes \mathcal{F}. \tag{3}$$

II. EXISTENCE AND UNIQUENESS

In this section we discuss existence and uniqueness for the quaternionic initial value problem

$$\Psi'' = \alpha \Psi' + \beta \Psi + \rho, \quad \Psi(x_0) = f, \quad \Psi'(x_0) = g, \tag{4}$$

with $\alpha(x), \beta(x), \rho(x) \in \mathbb{H} \otimes \mathcal{F}$, $x_0 \in I: (x_-, x_+)$ and $f, g \in \mathbb{H}$.

Theorem 1: Let α, β , and ρ in Eq. (4) be continuous functions of x on an open interval I containing the point $x = x_0$. Then, the initial value problem (4) has a solution Ψ on this interval and this solution is unique.

Proof: By using the real matrix representation (3), we can immediately rewrite the quaternionic initial value problem (4) in the following vector form:

$$\begin{bmatrix} \Psi_0 \\ \Psi_1 \\ \Psi_2 \\ \Psi_3 \end{bmatrix}'' = \begin{pmatrix} \alpha_0 & -\alpha_1 & -\alpha_2 & -\alpha_3 \\ \alpha_1 & \alpha_0 & -\alpha_3 & \alpha_2 \\ \alpha_2 & \alpha_3 & \alpha_0 & -\alpha_1 \\ \alpha_3 & -\alpha_2 & \alpha_1 & \alpha_0 \end{pmatrix} \begin{bmatrix} \Psi_0 \\ \Psi_1 \\ \Psi_2 \\ \Psi_3 \end{bmatrix}' + \begin{pmatrix} \beta_0 & -\beta_1 & -\beta_2 & -\beta_3 \\ \beta_1 & \beta_0 & -\beta_3 & \beta_2 \\ \beta_2 & \beta_3 & \beta_0 & -\beta_1 \\ \beta_3 & -\beta_2 & \beta_1 & \beta_0 \end{pmatrix} \begin{bmatrix} \Psi_0 \\ \Psi_1 \\ \Psi_2 \\ \Psi_3 \end{bmatrix} + \begin{bmatrix} \rho_0 \\ \rho_1 \\ \rho_2 \\ \rho_3 \end{bmatrix} \tag{5}$$

with

$$\begin{bmatrix} \Psi_0(x_0) \\ \Psi_1(x_0) \\ \Psi_2(x_0) \\ \Psi_3(x_0) \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} \Psi_0'(x_0) \\ \Psi_1'(x_0) \\ \Psi_2'(x_0) \\ \Psi_3'(x_0) \end{bmatrix} = \begin{bmatrix} g_0 \\ g_1 \\ g_2 \\ g_3 \end{bmatrix}. \tag{6}$$

Equation (5) represents a (nonhomogeneous) linear system with $\alpha_m, \beta_m, \rho_m \in \mathbb{R} \otimes \mathcal{F}$, where $m = 0, 1, 2, 3$. These functions are (see hypothesis of Theorem 1) continuous (real) functions of x on an open interval I containing the point $x = x_0$. Then, by a well-known theorem of analysis, see, for example, Ref. 7, the linear system (5) has a solution

$$\begin{bmatrix} \Psi_0 \\ \Psi_1 \\ \Psi_2 \\ \Psi_3 \end{bmatrix} \in \mathbb{R}^4 \otimes \mathcal{F}$$

on this interval satisfying (6), and this solution is unique. ■

III. LINEAR INDEPENDENCE AND DEPENDENCE OF SOLUTIONS

Let us now analyze the linear independence and dependence of the solutions of second order homogeneous differential equations

$$\Psi'' = \alpha \Psi' + \beta \Psi, \tag{7}$$

where α and β are (quaternionic) continuous functions of x on an open interval I . Equation (7) is linear over \mathbb{H} from the right. Consequently, if φ is a solution of Eq. (7) only the function obtained by right multiplication by constant quaternionic coefficients, φu , still represent a solution of such an equation. The general solution of Eq. (7) is given in terms of a pair of linearly independent solutions φ and ξ by

$$\Psi = \varphi u + \xi v, \tag{8}$$

where $\varphi = \varphi_0 + i \varphi_1 + j \varphi_2 + k \varphi_3$, $\xi = \xi_0 + i \xi_1 + j \xi_2 + k \xi_3 \in \mathbb{H} \otimes \mathcal{F}$, and $u, v \in \mathbb{H}$.

In the standard complex theory ($\varphi = \varphi_0 + i \varphi_1$ and $\xi = \xi_0 + i \xi_1 \in \mathbb{C} \otimes \mathcal{F}$) a useful criterion to establish linear independence and dependence of two solutions of homogeneous second order differential equation, uses the concept of *Wronskian* of these solutions defined by

$$W = \varphi \xi' - \varphi' \xi, \quad W \in \mathbb{C} \otimes \mathcal{F}. \tag{9}$$

This definition cannot be extended to quaternionic functions. Let us consider two linearly dependent solutions of Eq. (7),

$$\xi = \varphi q, \quad \varphi, \xi \in \mathbb{H} \otimes \mathcal{F}, \quad q \in \mathbb{H}. \tag{10}$$

By substituting $\xi = \varphi q$ and $\xi' = \varphi' q$ in the *Wronskian* (9), we find

$$\varphi \xi' - \varphi' \xi = \varphi \varphi' q - \varphi' \varphi q \neq 0.$$

Observe that a quaternionic function and its first derivative do not, in general, commute. Thus, the definition (9), and all its possible factor combinations cannot be extended to the quaternionic case.

Let us now use the linear dependence condition (10) to investigate the possibility to define a quaternionic functional which extends (in a nontrivial way) the standard (complex) *Wronskian* to the noncommutative case. From Eq. (10) and its derivative, we get

$$q = \varphi^{-1} \xi = (\varphi')^{-1} \xi',$$

where $\varphi^{-1} \equiv 1/\varphi$ and $(\varphi')^{-1} \equiv 1/\varphi'$. Consequently, for linearly dependent quaternionic solutions, we have

$$\xi' - \varphi' \varphi^{-1} \xi = 0. \tag{11}$$

To recover, in the complex limit, the standard definition (9) we multiply $\xi' - \varphi' \varphi^{-1} \xi$ by φ . Due to the noncommutative nature of quaternions, we have to consider the following possibilities:

$$W_L = \varphi (\xi' - \varphi' \varphi^{-1} \xi) \quad \text{and} \quad W_R = (\xi' - \varphi' \varphi^{-1} \xi) \varphi. \tag{12}$$

Obviously two other *similar* definitions can be obtained by $\varphi \leftrightarrow \xi$,

$$\tilde{W}_L = -\xi (\varphi' - \xi' \xi^{-1} \varphi) = -W_L[\varphi \leftrightarrow \xi] \quad \text{and} \quad \tilde{W}_R = -(\varphi' - \xi' \xi^{-1} \varphi) \xi = -W_R[\varphi \leftrightarrow \xi]. \tag{13}$$

The quaternionic functionals (12) and (13), which give in the complex limit the standard definition, extend a first important property of *Wronskian*. Two solutions of Eq. (7) are linearly dependent on I if $W_{L(R)} [\tilde{W}_{L(R)}]$ is zero on I . To avoid ambiguity in defining the *Wronskian*, we shall introduce a (real) functional,

$$|W|^2 = |W_L|^2 = |W_R|^2 = |\tilde{W}_L|^2 = |\tilde{W}_R|^2,$$

which extends the *squared absolute value* of the *Wronskian*. This *unique* functional is

$$|W|^2 = |\varphi|^2 |\xi'|^2 + |\xi|^2 |\varphi'|^2 - \varphi' \varphi_c \xi \xi'_c - \xi' \xi_c \varphi \varphi'_c \in \mathbb{R} \otimes \mathcal{F}, \tag{14}$$

where $\varphi_c = \varphi_0 - i \varphi_1 - j \varphi_2 - k \varphi_3$ and $\xi_c = \xi_0 - i \xi_1 - j \xi_2 - k \xi_3$ are, respectively, the quaternionic conjugate functions of φ and ξ .

Observe that Eq. (14) can also be obtained as an application of the Dieudonné theory of quaternionic determinants.⁸⁻¹² In fact,

$$|W|^2 = [\text{Det}(M)]^2 := \det(M M^+), \tag{15}$$

where

$$M = \begin{pmatrix} \varphi & \xi \\ \varphi' & \xi' \end{pmatrix}.$$

Theorem 2: Let α and β in Eq. (7) be continuous functions of x on an open interval $I : (a, b)$. Then, two solutions φ and ξ of Eq. (7) on I are linearly dependent on I if and only if the *absolute value* of the *Wronskian*, $|W|$, is zero at some x_0 in I .

The proof will be divided into three steps:

- (a) If φ and ξ are linearly dependent on I then $|W| = 0$.
- (b) If $|W| = 0$ at some x_0 in I then $|W| = 0$ on I .
- (c) If $|W| = 0$ at some x_0 in I then φ and ξ are linearly dependent on I .

Proof (a): If φ and ξ are linearly dependent on I , then Eq. (10) holds on I . From Eq. (10), we get

$$|W|^2 = |\varphi|^2 |\varphi'|^2 |q|^2 + |\varphi|^2 |\varphi'|^2 |q|^2 - \varphi' \varphi_c \varphi |q|^2 \varphi'_c - \varphi' |q|^2 \varphi_c \varphi \varphi'_c = 0,$$

then $|W| = 0$.

Proof (b): Let us consider Eq. (14). By calculating the first derivative of the left-hand- and right-hand-side terms, we obtain

$$\begin{aligned} 2 |W| |W'| &= \varphi' \varphi_c \xi' \xi'_c + \varphi \varphi'_c \xi' \xi'_c + \varphi \varphi_c \Psi''_2 \xi'_c + \varphi \varphi_c \xi' \xi''_c + \xi' \xi_c \varphi' \varphi'_c + \xi \xi'_c \varphi' \varphi'_c \\ &\quad + \xi \xi_c \Psi''_1 \varphi'_c + \xi \xi_c \varphi' \varphi''_c - \Psi''_1 \varphi_c \xi \xi'_c - \varphi' \varphi'_c \xi \xi'_c - \varphi' \varphi_c \xi' \xi'_c - \varphi' \varphi_c \xi \xi''_c \\ &\quad - \Psi''_2 \xi_c \varphi \varphi'_c - \xi' \xi'_c \varphi \varphi'_c - \xi' \xi_c \varphi' \varphi'_c - \xi' \xi_c \varphi \varphi''_c \\ &= |\varphi|^2 (\Psi''_2 \xi'_c + \xi' \xi''_c) + |\xi|^2 (\Psi''_1 \varphi'_c + \varphi' \varphi''_c) - \Psi''_1 \varphi_c \xi \xi'_c - \varphi' \varphi_c \xi \xi''_c \\ &\quad - \Psi''_2 \xi_c \varphi \varphi'_c - \xi' \xi_c \varphi \varphi''_c \\ &= |\varphi|^2 (\alpha |\xi'|^2 + \beta \xi \xi'_c + \text{h.c.}) + |\xi|^2 (\alpha |\varphi'|^2 + \beta \varphi \varphi'_c + \text{h.c.}) \\ &\quad - [(\alpha \varphi' \varphi_c + \beta |\varphi|^2) \xi \xi'_c + \text{h.c.}] - [(\alpha \xi' \xi_c + \beta |\xi|^2) \varphi \varphi'_c + \text{h.c.}] \\ &= 2 \text{Re}[\alpha] (|\varphi|^2 |\xi'|^2 + |\xi|^2 |\varphi'|^2 - \varphi' \varphi_c \xi \xi'_c - \xi' \xi_c \varphi \varphi'_c) = 2 \text{Re}[\alpha] |W|^2. \end{aligned}$$

By a simple integration, we find

$$|W(x)| = \exp\left[\int_{x_0}^x \operatorname{Re}[\alpha(y)] dy\right] |W(x_0)|. \tag{16}$$

This proves the statement (b).

Proof (c): From the statement (b), we have

$$|W(x_0)| = 0 \Rightarrow |W(x)| = 0, \quad x \in I.$$

This implies that the quaternionic matrix

$$\begin{pmatrix} \varphi & \xi \\ \varphi' & \xi' \end{pmatrix}$$

is not invertible on I .¹² Hence the linear system

$$\varphi q_1 + \xi q_2 = 0, \quad \varphi' q_1 + \xi' q_2 = 0,$$

in the unknowns $q_{1,2} \in \mathbb{H}$, has a solution (q_1, q_2) where q_1 and q_2 are not both zero. Recalling that φ and ξ are linearly independent on an interval I if

$$\varphi(x) q_1 + \xi(x) q_2 = 0 \Rightarrow q_1 = q_2 = 0,$$

the fact that q_1 and q_2 are not both zero guarantees the linear dependence of φ and ξ on I . ■

Example 1: Show that $\varphi = \exp[-ix]$ and $\xi = \exp[(i-j)x]$ form a basis of solutions of

$$\Psi'' + j \Psi' + (1-k) \Psi = 0, \tag{17}$$

on any interval.

Solution: Substitution shows that they are solutions,

$$[-1 + j(-i) + 1 - k] \exp[-ix] = 0,$$

$$[-2 + j(i-j) + 1 - k] \exp[(i-j)x] = 0,$$

and linear independence follows from Theorem 2, since

$$|W| = \sqrt{|i-j|^2 + |i|^2 + i(j-i) - (i-j)i} = \sqrt{5}.$$

IV. HOMOGENEOUS EQUATIONS: REDUCTION OF ORDER

Let φ be solution of Eq. (7) on some interval I . Looking for a solution in the form

$$\xi = \varphi \tau$$

and substituting ξ and its derivatives

$$\xi' = \varphi' \tau + \varphi \tau' \quad \text{and} \quad \xi'' = \varphi'' \tau + 2 \varphi' \tau' + \varphi \tau''$$

into Eq. (7), we obtain

$$\tau'' = (\varphi^{-1} \alpha \varphi - 2 \varphi^{-1} \varphi') \tau'. \tag{18}$$

It is important to observe that, for quaternionic functions, we *cannot* give a formal solution of the previous equation. Only in particular cases, Eq. (18) can be immediately integrated. For example, for homogeneous second order equations with constant coefficients,

$$\alpha(x) \rightarrow a \in \mathbb{H} \quad \text{and} \quad \beta(x) \rightarrow b \in \mathbb{H},$$

at least one solution is in the form of a quaternionic exponential, $\varphi = \exp[qx]$, and consequently Eq. (18) reduces to

$$\varphi \tau'' = (a - 2q) \varphi \tau'. \tag{19}$$

Let us introduce the quaternionic function

$$\sigma = \varphi \tau'.$$

Observing that

$$\sigma' = \varphi' \tau' + \varphi \tau'' = q \varphi \tau' + \varphi \tau'',$$

Eq. (19) can be rewritten as follows:

$$\sigma' = (a - q) \sigma. \tag{20}$$

This equation can be immediately integrated, its solution reads

$$\sigma = \exp[(a - q)x].$$

Thus, the second solution of the homogeneous second order differential equation with constant coefficients is given by

$$\xi = \exp[qx] \int \exp[-qx] \exp[(a - q)x] dx. \tag{21}$$

In the complex limit ($a, q \in \mathbb{C}$) we find the well-known results $\xi \propto \exp[(a - q)x]$ if $2q \neq a$ and $\xi \propto x \exp[qx]$ if $2q = a$. In the quaternionic case ($a, q \in \mathbb{C}$), the integral which appears in (21) must be treated with care. The solution of this integral will give interesting information about the second solution of quaternionic differential equations with constant coefficients when the associated characteristic quadratic equation has a unique solution. To solve the integral in Eq. (21), we start by observing that

$$[e^{ux} e^{vx}]' = u e^{ux} e^{vx} + e^{ux} e^{vx} v = (L_u + R_v) e^{ux} e^{vx}.$$

If the operator $L_u + R_v$ is invertible the previous equality implies

$$\int e^{ux} e^{vx} dx = (L_u + R_v)^{-1} e^{ux} e^{vx}.$$

This result guarantees that, if the operator $L_{-q} - R_{a-q}$ is invertible the second solution can be written in the form

$$\begin{aligned} \xi &= \exp[qx] (L_{-q} + R_{a-q})^{-1} \exp[-qx] \exp[(a - q)x] \\ &= \exp[qx] (R_{a-q} - L_q)^{-1} \exp[-qx] \exp[(a - q)x]. \end{aligned} \tag{22}$$

If the operator $L_{-q} + R_{a-q}$ is *not* invertible, we need to solve the integral which appears in (21) by using the polar decomposition of quaternions (see example 3) and a term linearly dependent on x

will appear. In the complex case $(a, q \in \mathbb{C})$, the operator $L_{-q} + R_{a-q}$ is not invertible if and only if $2q = a$. In the quaternionic $(a, q \in \mathbb{H})$, the condition $2q \neq a$ does not guarantee that the operator is invertible.

Example 2: Knowing that $\varphi = \exp[-ix]$ is solution of the homogeneous second order equation (17), find (by using the method of reduction of order) a second independent solution, ξ .

Solution: We have $q = -i$ and $a = -j$. To use Eq. (22) we have to prove that the operator

$$L_{-q} + R_{a-q} = L_i + R_{i-j}$$

is invertible. A simple algebraic calculation shows that

$$(L_i - R_{i-j})(L_i + R_{i-j}) = 1.$$

Thus,

$$(L_{-q} + R_{a-q})^{-1} = L_i - R_{i-j}.$$

We are now ready to calculate ξ from Eq. (22),

$$\xi = \exp[-ix] (L_i - R_{i-j}) \exp[ix] \exp[(i-j)x] = (L_i - R_{i-j}) \exp[(i-j)x] = \exp[(i-j)x] j.$$

Due to the \mathbb{H} linearity (from the right) of Eq. (17) the right factor j can be ignored recovering the solution of example 1.

Example 3: Inspection shows that

$$\Psi'' + i \Psi' + \frac{k}{2} = 0 \tag{23}$$

has $\varphi = \exp\{-[(i+j)/2]x\}$ as a first solution. Find the second linear independent solution.

Solution: We have $q = -(i+j)/2$ and $a = -i$. In this case, the operator

$$L_{-q} + R_{a-q} = L_{(i+j)/2} + R_{(j-i)/2}$$

is *not* invertible. This is easily seen by using, for example, the real matrix representation (3). Thus, the integral in Eq. (21) cannot be expressed in terms of an exponential product. Let us explicitly calculate ξ from Eq. (21). We find

$$\begin{aligned} \xi &= \exp\left[-\frac{i+j}{2}x\right] \int \exp\left[\frac{i+j}{2}x\right] \exp\left[\frac{j-i}{2}x\right] dx \\ &= \exp\left[-\frac{i+j}{2}x\right] \int \left(\cos \frac{x}{\sqrt{2}} + \frac{i+j}{\sqrt{2}} \sin \frac{x}{\sqrt{2}}\right) \left(\cos \frac{x}{\sqrt{2}} + \frac{j-i}{\sqrt{2}} \sin \frac{x}{\sqrt{2}}\right) dx \\ &= \exp\left[-\frac{i+j}{2}x\right] \int \{1 - k \exp[-(i+j)x]\} \frac{1+k}{2} dx. \end{aligned}$$

Due to the \mathbb{H} linearity (from the right) of Eq. (23) the right factor $(1+k)/2$ can be removed. After integration, we find

$$\xi = \exp\left[-\frac{i+j}{2}x\right] \left\{ x - k \frac{i+j}{2} \exp[-(i+j)x] \right\} = \left(x + \frac{i-j}{2}\right) \exp\left[-\frac{i+j}{2}x\right].$$

Observe that the quaternionic factor $(i-j)/2$ appears on the left of the quaternionic exponential and consequently *cannot* be removed. It is a fundamental part of the solution. Inspection shows that

$$\xi = x \exp \left[-\frac{i+j}{2} x \right]$$

is *not* the solution of Eq. (23).

V. NONHOMOGENEOUS EQUATIONS: VARIATION OF PARAMETERS

A general solution of the nonhomogeneous equation (4) is a solution of the form

$$\Psi = \Psi_h + \Psi_p, \tag{24}$$

where

$$\Psi_h = \varphi q_1 + \xi q_2$$

is a general solution of the homogeneous equation (7) and Ψ_p is any particular solution of (4) containing no arbitrary constants. In this section we discuss the so-called method of variation of parameters to find a particular solution for quaternionic nonhomogeneous differential equations.

A method to solve a homogeneous second order quaternionic differential equations with constant coefficients has been recently developed.² Quaternionic differential equations with non-constant coefficients are under investigation. We suppose to know two independent solutions of the homogeneous equation associated with Eq. (7). We wish to investigate if the method of variation of parameters still works in the quaternionic case.

The method of variation of parameters involves replacing the constant q_1 and q_2 by quaternionic functions $\nu_1(x)$ and $\nu_2(x)$ to be determined so that the resulting function

$$\Psi_p = \varphi \nu_1 + \xi \nu_2$$

is a particular solution of Eq. (4). By differentiating Ψ_p we obtain

$$\Psi_p' = \varphi' \nu_1 + \xi' \nu_2 + \varphi \nu_1' + \xi \nu_2'.$$

The requirement that Ψ_p satisfies Eq. (4) imposes only *one* condition on ν_1 and ν_2 . Hence, we can impose a second arbitrary condition, that is

$$\varphi \nu_1' + \xi \nu_2' = 0. \tag{25}$$

This reduces Ψ_p' to the form

$$\Psi_p' = \varphi' \nu_1 + \xi' \nu_2.$$

By differentiating this function we have

$$\Psi_p'' = \varphi'' \nu_1 + \varphi' \nu_1' + \xi'' \nu_2 + \xi' \nu_2'.$$

Substituting Ψ_p , Ψ_p' , and Ψ_p'' in Eq. (4) we readily obtain

$$\varphi' \nu_1' + \xi' \nu_2' = \rho. \tag{26}$$

Collecting Eq. (25) and Eq. (26), we can construct the following matrix system:

$$\begin{pmatrix} \varphi & \xi \\ \varphi' & \xi' \end{pmatrix} \begin{bmatrix} \nu_1' \\ \nu_2' \end{bmatrix} = \begin{bmatrix} 0 \\ \rho \end{bmatrix}, \tag{27}$$

from which ($|W| \neq 0$) we obtain

$$\begin{bmatrix} \nu'_1 \\ \nu'_2 \end{bmatrix} = \begin{pmatrix} \varphi & \xi \\ \varphi' & \xi' \end{pmatrix}^{-1} \begin{bmatrix} 0 \\ \rho \end{bmatrix} = \begin{pmatrix} [\varphi - \xi \xi'^{-1} \varphi']^{-1} & [\varphi' - \xi' \xi^{-1} \varphi]^{-1} \\ [\xi - \varphi \varphi'^{-1} \xi']^{-1} & [\xi' - \varphi' \varphi^{-1} \xi]^{-1} \end{pmatrix} \begin{bmatrix} 0 \\ \rho \end{bmatrix}. \tag{28}$$

Then,

$$\nu'_1 = [\varphi' - \xi' \xi^{-1} \varphi]^{-1} \rho \quad \text{and} \quad \nu'_2 = [\xi' - \varphi' \varphi^{-1} \xi]^{-1} \rho. \tag{29}$$

To find $\nu_1(x)$ and $\nu_2(x)$ we have to integrate the previous equations.

Example 4: Find a general solution of the nonhomogeneous quaternionic differential equation

$$\Psi'' + j \Psi' + (1 - k) \Psi = i x. \tag{30}$$

Solution: The solution of the associated homogeneous equation (see example 1) is

$$\Psi_h = \exp[-ix] q_1 + \exp[-(i+j)x] q_2.$$

The particular solution is

$$\Psi_p = \exp[-ix] \nu_1 + \exp[-(i+j)x] \nu_2.$$

Consequently, from Eqs. (29) we find

$$\nu'_1 = \exp[ix] x k \quad \text{and} \quad \nu'_2 = -\exp[(i+j)x] x k$$

which after integration give

$$\nu_1(x) = (1 - ix) \exp[ix] k \quad \text{and} \quad \nu_2(x) = -\frac{1}{2} [1 - (i+j)x] \exp[(i+j)x] k.$$

Finally

$$\Psi_p = \frac{1}{2} [(i+j)x + k].$$

A general solution of Eq. (23) is

$$\Psi = \exp[-ix] q_1 + \exp[-(i+j)x] q_2 + \frac{1}{2} [(i+j)x + k].$$

VI. CONCLUSIONS AND OUTLOOKS

The recent results on violations of quantum mechanics by quaternionic potentials¹ and the possibility to get a better understanding of CP-violation phenomena within a quaternionic formulation of physical theories^{1,13} stimulated the study of quaternionic differential operators.² In this paper, we have proved existence and uniqueness for quaternionic initial value problems and solved simple quaternionic differential equations by discussing the reduction of order for quaternionic homogeneous equations and by extending to the noncommutative case the method of variation of parameters and the definition of absolute value of the Wronskian functional.

In view of a more complete discussion of quantum dynamical systems using quaternionic wave packets, our next research (mathematical) interest will be the study of quaternionic integral transforms. The quaternionic formulation of Fourier transforms could find an immediate and interesting application in the study of delay time modifications of wave packets scattered by a quaternionic potential step.

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