

Regularity structures – Exercise sessions

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Goal of those sessions

Consider gaussian white-noise ξ , parameters $\alpha, \beta \in \mathbb{R}$.
Throughout these sessions we will study

$$(-\Delta)\phi = (\alpha + \beta\phi)\xi, \quad x \in \mathbb{R}^d. \quad (\text{E})$$

We will be interested in $d = 1, d = 2$.

Goal: Show some useful tools and explain why

- 1 if $d = 1$: (E) admits (local) solutions;
- 2 if $d = 2$: for natural smooth approximations ξ_ϵ of ξ , there exist $C_\epsilon \in \mathbb{R}$ s.t. the renormalised equations

$$(-\Delta)\phi_\epsilon = (\alpha + \beta\phi_\epsilon)(\xi_\epsilon - \beta C_\epsilon),$$

admit solutions converging to some (non-trivial) ϕ .

Equation (E) is a “pretext” to illustrate on a simple case some of the

- analytic aspects,
 - probabilistic aspects,
- of regularity structures.

However: we will not discuss the algebraic aspects.

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Session 1

First remarks on (E)

A few remarks

$$(-\Delta)\phi = (\alpha + \beta\phi)\xi, \quad x \in \mathbb{R}^d. \quad (\text{E})$$

Some (heuristic) remarks:

- this is an elliptic equation;
- we might have to play with α, β to obtain contractivity for Picard fixed-point;
- we might want to work on torus \mathbb{T}^d rather than \mathbb{R}^d to benefit from boundedness;
- the regularity of ξ decreases when d increases so we expect the equation to be more difficult to discuss;
- for simplicity we will not consider questions of uniqueness/boundary conditions.

We will replace (E) by its mild formulation

$$\phi = K * ((\alpha + \beta\phi)\xi), \quad (M)$$

where $K = “(-\Delta)^{-1}”$ is the fundamental solution of the Laplacian,

$$K(x) = -\frac{1}{2}|x| \quad (d = 1), \quad K(x) = -\frac{1}{2\pi} \log |x| \quad (d = 2).$$

Question: in which space could we set up a fixed-point for (M)?

Classical Hölder functions

Definition

Let $\alpha \in (0, 1)$, and $\phi: \mathbb{R}^d \rightarrow \mathbb{R}$. We say that ϕ is α -Hölder if

$$|\phi(y) - \phi(x)| \lesssim |y - x|^\alpha.$$

More generally.

Definition

Let $\alpha \in \mathbb{R}_+ \setminus \mathbb{N}$, and $\phi: \mathbb{R}^d \rightarrow \mathbb{R}$. We say that ϕ is α -Hölder if

$$\left| \phi(y) - \sum_{|k| \leq \alpha} \frac{\phi^{(k)}(x)}{k!} (y - x)^k \right| \lesssim |y - x|^\alpha.$$

What about distributions?

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What about distributions?

Measuring regularity: the Hölder spaces

Quick calculation: if $|\phi(x) - \phi(y)| \lesssim |y - x|^\alpha$, then

$$\phi(\eta_x^\lambda) = \int \phi(y) \eta_x^\lambda(y) dy = \int \phi(x + \lambda y) \eta(y) dy = O(1).$$

If $\int \eta = 0$, then

$$\phi(\eta_x^\lambda) = \int (\phi(x + \lambda y) - \phi(x)) \eta(y) dy = O(\lambda^\alpha).$$

Measuring regularity: the Hölder spaces

Generally: define

$$\mathcal{B}_\alpha^r := \left\{ \eta \in \mathcal{D}(B(0,1)), \|\eta\|_{C^r} \leq 1, \int \eta(x) x^k dx = 0 \text{ for } 0 \leq |k| \leq \alpha \right\}.$$

And for $\alpha \in \mathbb{R}$, $r > -\alpha$, $K \subset \mathbb{R}^d$

$$\|\phi\|_{C_K^\alpha} = \sup_{x \in K, \eta \in \mathcal{B}^r} |\phi(\eta_x)| + \sup_{x \in K, \lambda \in (0,1], \eta \in \mathcal{B}_\alpha^r} \frac{|\phi(\eta_x^\lambda)|}{\lambda^\alpha}, \quad (1)$$

Definition (Local Hölder spaces)

For $\alpha \in \mathbb{R}$, $\mathcal{C}_{\text{loc}}^\alpha$ is the complete metrizable space corresponding to the family of seminorms (1).

When $\alpha \in \mathbb{R}_+ \setminus \mathbb{N}$, $\mathcal{C}_{\text{loc}}^\alpha$ coincides with the classical Hölder functions.

Some natural questions about Hölder spaces:

- 1 what is gaussian white-noise ξ and what is its Hölder regularity?
- 2 when is pointwise multiplication $\mathcal{C}_{\text{loc}}^{\alpha} \times \mathcal{C}_{\text{loc}}^{\beta} \rightarrow \mathcal{C}_{\text{loc}}^{\gamma}$ well-defined and continuous?
- 3 when is convolution $K: \mathcal{C}_{\text{loc}}^{\alpha} \rightarrow \mathcal{C}_{\text{loc}}^{\beta}$ well-defined and continuous?

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Gaussian white noise

Definition (Gaussian white noise)

Let $(H, \langle \cdot, \cdot \rangle)$ be a Hilbert space. A *gaussian white noise* on H is a linear isometry

$$\begin{aligned}\xi: H &\rightarrow L^2(\Omega, \mathcal{F}, \mathbb{P}) \\ h &\mapsto \xi(h),\end{aligned}$$

on some probability space $(\Omega, \mathcal{F}, \mathbb{P})$ such that for all $h \in H$, $\xi(h)$ is a real-valued centered gaussian variable.

NB: the isometry property means that for $h_1, h_2 \in H$, $\mathbb{E}[\xi(h_1)\xi(h_2)] = \langle h_1, h_2 \rangle$. In particular, $\xi(h) \sim \mathcal{N}(0, \|h\|^2)$.

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Kolmogorov's continuity theorem for distributions

ξ eats test-functions. Is it a Hölder distribution?

Theorem (Kolmogorov's continuity for distributions)

Let $X: L^2(\mathbb{R}^d) \rightarrow L^2(\Omega, \mathcal{F}, \mathbb{P})$ be a continuous map. Assume there exist $\alpha \in \mathbb{R}$, $p \geq 1$ such that for all $\eta \in L^2(\mathbb{R}^d)$, $k \in \mathbb{N}$, $x \in \mathbb{R}^d$,

$$\mathbb{E}[|X(\eta_x^{2^{-k}})|^p] \leq C_{p,\eta} 2^{-k\alpha p}.$$

Then there exists $\tilde{X}: L^2(\mathbb{R}^d) \rightarrow L^2(\Omega, \mathcal{F}, \mathbb{P})$ such that

- 1 for all $\eta \in L^2(\mathbb{R}^d)$, $\tilde{X}(\eta) = X(\eta)$ almost surely,
- 2 for all $\omega \in \Omega$, and $\alpha' < \alpha - d/p$, $\tilde{X}(\omega) \in \mathcal{C}_{\text{loc}}^{\alpha'}(\mathbb{R}^d)$.

Technique of proof: use dyadic decompositions, such as wavelets or Littlewood-Paley decompositions.

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Technique of proof: use dyadic decompositions, such as wavelets or Littlewood-Paley decompositions.

Let us check that ξ satisfies the condition for $\alpha = -d/2$.

$$\begin{aligned}\mathbb{E}\left[|\xi(\eta_x^{2^{-k}})|^p\right] &\leq C_p \mathbb{E}\left[|\xi(\eta_x^{2^{-k}})|^2\right]^{p/2} && \text{(gaussian moments)} \\ &= C_p \|\eta_x^{2^{-k}}\|_{L^2}^p && \text{(isometry)}\end{aligned}$$

But:

$$\begin{aligned}\|\eta_x^{2^{-k}}\|_{L^2}^2 &= \int \eta_x^{2^{-k}}(y) \eta_x^{2^{-k}}(y) dy \\ &= \int 2^{kd} \eta(2^k(y-x)) 2^{kd} \eta(2^k(y-x)) dy \\ &= \int 2^{kd} \eta(u)^2 du = 2^{kd} \|\eta\|_{L^2}^2.\end{aligned}$$

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Consequence:

Proposition

Any gaussian white-noise ξ on \mathbb{R}^d has a modification which belongs to $\mathcal{C}_{\text{loc}}^{-d/2-\kappa}(\mathbb{R}^d)$ for all $\kappa > 0$.

In fact, exploiting gaussianity in a smarter way one can prove

Proposition

Any gaussian white-noise ξ on \mathbb{R}^d has a modification which belongs to the Besov space $\mathcal{B}_{p,\infty;\text{loc}}^{-d/2}(\mathbb{R}^d)$ for all $p \in [1, \infty)$.

This is slightly stronger because $\mathcal{B}_{p,\infty;\text{loc}}^{-d/2}(\mathbb{R}^d) \subset \mathcal{C}_{\text{loc}}^{-d/2-d/p}(\mathbb{R}^d)$.

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Direct Picard iteration works in $d = 1$

Recall the situation:

$$\phi = K * ((\alpha + \beta\phi)\xi). \quad (\text{M})$$

We want to solve (M) as a Picard fixed-point in some $\mathcal{C}_{\text{loc}}^\alpha(\mathbb{R}^d)$.
In this section we start with the case $d = 1$.

We asked three questions about Hölder spaces:

- 1 what is gaussian white-noise ξ and what is its Hölder regularity?
- 2 when is pointwise multiplication $\mathcal{C}_{\text{loc}}^{\alpha} \times \mathcal{C}_{\text{loc}}^{\beta} \rightarrow \mathcal{C}_{\text{loc}}^{\gamma}$ well-defined and continuous?
- 3 when is convolution $K: \mathcal{C}_{\text{loc}}^{\alpha} \rightarrow \mathcal{C}_{\text{loc}}^{\beta}$ well-defined and continuous?

Hölder spaces question 1: white noise

Question

What is gaussian white-noise ξ and what is its Hölder regularity?

Answer

$\xi \in \mathcal{C}_{\text{loc}}^{-d/2-\kappa}$ for any $\kappa > 0$. For $d = 1$: $\xi \in \mathcal{C}_{\text{loc}}^{-1/2-\kappa}$.

Hölder spaces question 2: Young multiplication

Question

When is pointwise multiplication $\mathcal{C}_{\text{loc}}^\alpha \times \mathcal{C}_{\text{loc}}^\beta \rightarrow \mathcal{C}_{\text{loc}}^\gamma$ well-defined and continuous?

Answer (Young multiplication)

The product $\mathcal{C}_{\text{loc}}^\alpha \times \mathcal{C}_{\text{loc}}^\beta \rightarrow \mathcal{C}_{\text{loc}}^{\min(\alpha,\beta)}$ is canonically well-defined iff $\alpha + \beta > 0$, with continuity bounds

$$\|fg\|_{\mathcal{C}_K^{\min(\alpha,\beta)}} \leq C_{\alpha,\beta} \|f\|_{\mathcal{C}_{K \oplus B(0,A)}^\alpha} \|g\|_{\mathcal{C}_{K \oplus B(0,A)}^\beta},$$

for some $A \geq 0$.

Hölder spaces question 3: classical Schauder estimates

Question

When is convolution $K: \mathcal{C}_{\text{loc}}^\alpha \rightarrow \mathcal{C}_{\text{loc}}^\beta$ well-defined and continuous?

Answer (Schauder estimates)

For any $\alpha \in \mathbb{R}$, $K: \mathcal{C}_{\text{loc}}^\alpha \rightarrow \mathcal{C}_{\text{loc}}^{\alpha+2}$ with continuity bounds

$$\|K * f\|_{\mathcal{C}_K^{\alpha+2}} \leq C_\alpha \|f\|_{\mathcal{C}_{K \oplus B(0,A)}^\alpha},$$

for some $A \geq 0$.

First terms of Picard iteration

Let us perform Picard iteration (recall $\xi \in \mathcal{C}_{\text{loc}}^{-1/2-\kappa}$):

$$\phi_{(0)} := 0 \quad \in C^\infty,$$

$$\begin{aligned} \phi_{(1)} &:= K * ((\alpha + \beta\phi_{(0)})\xi) \\ &= \alpha K * \xi \quad \in \mathcal{C}_{\text{loc}}^{3/2-\kappa} \text{ (Schauder),} \end{aligned}$$

$$\phi_{(2)} := K * ((\alpha + \beta\phi_{(1)})\xi) \quad \in \mathcal{C}_{\text{loc}}^{3/2-\kappa} \text{ (Schauder + Young).}$$

Young multiplication is justified because

$$\phi_{(1)} \in \mathcal{C}_{\text{loc}}^{3/2-\kappa}, \quad \xi \in \mathcal{C}_{\text{loc}}^{-1/2-\kappa}, \quad \frac{3}{2} - \kappa + \frac{-1}{2} - \kappa > 0.$$

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Conclusion: in $d = 1$, the iteration map

$$\begin{aligned}\mathcal{P}: C_{\text{loc}}^{3/2-\kappa} &\rightarrow C_{\text{loc}}^{3/2-\kappa} \\ \phi &\mapsto K * ((\alpha + \beta\phi)\xi),\end{aligned}$$

is well-defined with continuity estimates

$$\|\mathcal{P}(\phi_1) - \mathcal{P}(\phi_2)\|_{C_K^{3/2-\kappa}} \leq C\beta\|\xi\|_{C_{K\oplus B(0,A)}^{-1/2-\kappa}} \|\phi_1 - \phi_2\|_{C_{K\oplus B(0,A)}^{3/2-\kappa}}.$$

Subtlety: the Lipschitz constant depends on the compact K via the norm of the noise. Possible workarounds:

- construct solutions on bounded space (e.g. on the torus);
- work with weighted Hölder spaces.

In any case, \mathcal{P} becomes a contraction when setting β small enough.

NB: β might be random to construct ϕ a.s.; or if β is deterministic ϕ exists only with positive probability.

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Direct Picard iteration does not work in $d = 2$

First terms of Picard iteration

Let us try Picard iteration (here $d = 2$ so $\xi \in \mathcal{C}_{\text{loc}}^{-1-\kappa}$):

$$\begin{aligned}\phi_{(0)} &:= 0 && \in C^\infty, \\ \phi_{(1)} &:= K * ((\alpha + \beta\phi_{(0)})\xi) \\ &= \alpha K * \xi && \in \mathcal{C}_{\text{loc}}^{1-\kappa}, \\ \phi_{(2)} &\stackrel{?}{:=} K * ((\alpha + \beta\phi_{(1)})\xi) && \in ?\end{aligned}$$

Problem: $\phi_{(2)}$ has no canonical meaning because

$$\phi_{(1)} \in \mathcal{C}_{\text{loc}}^{1-\kappa}, \quad \xi \in \mathcal{C}_{\text{loc}}^{-1-\kappa}, \quad (1-\kappa) + (-1-\kappa) \leq 0.$$

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Da Prato–Debussche trick?

In this kind of situation, one could try:

Trick (Da Prato–Debussche, 2003)

Consider $\psi := \phi - \phi_{(1)}$ and try Picard iteration on ψ .

Interpretation: remove the term of “worst regularity”.

The fixed-point equation on ψ :

$$\psi = \phi - \phi_{(1)} = K * ((\alpha + \beta\phi)\xi) - \alpha K * \xi = \beta K * (\phi\xi).$$

i.e.

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In this kind of situation, one could try:

Trick (Da Prato–Debussche, 2003)

Consider $\psi := \phi - \phi_{(1)}$ and try Picard iteration on ψ .

Interpretation: remove the term of “worst regularity”.

The fixed-point equation on ψ :

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Problem: $\psi_{(2)}$ has no canonical meaning because

$$\psi_{(1)} \in \mathcal{C}_{\text{loc}}^{1-\kappa}, \quad \xi \in \mathcal{C}_{\text{loc}}^{-1-\kappa}, \quad (1-\kappa) + (-1-\kappa) \leq 0.$$

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Regularity vs homogeneity

Observation: if f, g are α resp. β -Hölder for $\alpha, \beta \in (0, 1)$, then

$$\begin{aligned} |f(y)g(y) - f(x)g(x)| &\lesssim |y - x|^{\min(\alpha, \beta)}, \\ |f(y) - f(x)||g(y) - g(x)| &\lesssim |y - x|^{\alpha + \beta}, \end{aligned}$$

where $\alpha + \beta > \min(\alpha, \beta)$.

Interpretation: the *germ* $(f(\cdot) - f(x))_{x \in \mathbb{R}^d}$ admits “nice” multiplicativity properties with respect to its *homogeneity*.

Heuristic conclusion: working in the world of germs might make the Picard iteration possible.

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Some reminders on germs

Definition (Germ)

A *germ* is a family $F = (F_x)_{x \in \mathbb{R}^d}$ of distributions $F_x \in \mathcal{D}'(\mathbb{R}^d)$.

Interpretation: a germ is a family of local approximations.

Basic example: if f is a $0 < \gamma$ -Hölder function, its Taylor germ:

$$T(f)_x(\cdot) = \sum_{|k| \leq \gamma} \frac{f^k(x)}{k!} (\cdot - x)^k.$$

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Definition (Coherence)

A germ F is (α, γ) -coherent if

$$|(F_y - F_x)(\varphi_x^\lambda)| \lesssim \lambda^\alpha (|y - x| + \lambda)^{\gamma - \alpha}$$

Definition (Homogeneity)

A germ F is $\bar{\alpha}$ -homogeneous if $|F_x(\varphi_x^\lambda)| \lesssim \lambda^{\bar{\alpha}}$.

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A bridge between germs and distributions is given by:

Theorem (Reconstruction, Hairer 2014, Caravenna-Zambotti 2020)

If F is (α, γ) -coherent for some $\gamma > 0$, then there exists a unique distribution $\mathcal{R}(F)$ such that $(\mathcal{R}(F) - F_x)_x$ is γ -homogeneous.

Example: if f is γ -Hölder, $\mathcal{R}(T(f)) = f$.

Useful particular case: if $x, y \mapsto F_x(y)$ is continuous, then

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We want to perform a fixed-point argument at the level of germs.
Question: can one perform the operations of convolution and multiplication at the level of germs?

Germes: Schauder estimates

Let K be the fundamental solution of the Laplacian.

Theorem (Schauder estimates for germs, L.B, F. Caravenna, L. Zambotti 2022)

Let F be an (α, γ) -coherent germ. Then the germ

$$\mathcal{K}(F)_x := K * F_x - \sum_{|k| < \gamma + 2} \frac{(K * \{F_x - \mathcal{R}(F)\})^{(k)}(x)}{k!} (\cdot - x)^k,$$

*is well-defined, $((\alpha + 2) \wedge 0, \gamma + 2)$ -coherent, and $\mathcal{R}(\mathcal{K}(F)) = K * \mathcal{R}(F)$.*

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Germes: products?

In general there is no canonical way of multiplying germs.

However, for continuous germs $x, y \mapsto F_x(y)$, $x, y \mapsto G_x(y)$, the germ $(FG)_x(y) := F_x(y)G_x(y)$ satisfies (if reconstruction is applicable)

$$\mathcal{R}(FG)(x) = F_x(x)G_x(x) = \mathcal{R}(F)(x)\mathcal{R}(G)(x).$$

Thank you for your attention!

Session 2

$d = 2$: the model

Basis germs II

Recall the situation:

$$\phi = K * ((\alpha + \beta\phi)\xi), \quad x \in \mathbb{R}^2.$$

Let ξ be gaussian white noise, ρ a test-function with $\int \rho = 1$, and $\xi_\epsilon = \xi * \rho^\epsilon$: this is a smooth approximation of ξ .

We consider the fixed-point equation on germs

$$F_\epsilon = \mathcal{K}((\alpha + \beta F_\epsilon)\xi_\epsilon).$$

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We need a nice complete metric space of germs in which to set up this fixed-point.

Let us try the Picard iteration:

$$\begin{aligned}(F_{\epsilon,(0)})_x &:= 0, \\(F_{\epsilon,(1)})_x &:= \mathcal{K}((\alpha + \beta F_{\epsilon,(0)})\xi_\epsilon)_x \\&= \alpha K * \xi_\epsilon \\&= \alpha \left(\underbrace{K * \xi_\epsilon - K * \xi_\epsilon(x)}_{1-\kappa \text{ homogeneous germ}} \right) + \alpha K * \xi_\epsilon(x) \underbrace{1}_{0\text{-hom.}}.\end{aligned}$$

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Pursuing the iteration: the germs of interest are of the form

$$\sum_i f_i(x) \Pi_x^{i,\epsilon},$$

for explicit homogeneous basis germ $\Pi^{i,\epsilon}$.

The first germs by order of homogeneity:

| Germ $\Pi_x^{i,\epsilon}(\cdot) =$ | Hom. α | Symbol |
|---|---------------|--------------|
| $\xi_\epsilon(\cdot)$ | $-1 - \kappa$ | \cdot |
| $(K * \xi_\epsilon(\cdot) - K * \xi_\epsilon(x)) \xi_\epsilon(\cdot)$ | -2κ | \dagger |
| $\xi_\epsilon(\cdot)(\cdot_1 - x_1)$ | $-\kappa$ | $\cdot X_1$ |
| $\xi_\epsilon(\cdot)(\cdot_2 - x_2)$ | $-\kappa$ | $\cdot X_2$ |
| 1 | 0 | $\mathbb{1}$ |
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Symbolic notation

We will use Hairer's symbolic notations:

- blue dot \cdot : represents the noise;
- bar: represents convolution (with K);
- symbolic multiplication (e.g. $\dot{\cdot} = \cdot \dot{\cdot}$, $\mathbb{1}\dot{\cdot} = \dot{\cdot}$) represents multiplication.

The notations simplify the expressions. Example:

$$\xi_\epsilon(y) + 3x(K * \xi_\epsilon(y) - K * \xi_\epsilon(x))\xi_\epsilon(y) = \Pi_x^\epsilon(\cdot + 3x\dot{\cdot})(y).$$

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Remark: for all (applicable) symbols τ, τ' ,

$$\Pi_x^\epsilon(\tau\tau') = \Pi_x^\epsilon(\tau)\Pi_x^\epsilon(\tau'),$$

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Reexpansion operator Γ

Fact

There exists a reexpansion operator Γ^ϵ defined by the relations

$$\Pi_y^{i,\epsilon} = \sum_j \Pi_x^{j,\epsilon} \Gamma_{x,y}^{j,i,\epsilon},$$

or in symbolic notation

$$\Pi_y^\epsilon(\tau) = \Pi_x^\epsilon(\Gamma_{x,y}^\epsilon(\tau)).$$

Let us calculate Γ^ϵ on some examples.

Example 0 (Polynomials)

Consider $\tau = X^k$.

We want $\Pi_x^\epsilon(\Gamma_{x,y}^\epsilon(X^k)) = \Pi_y^\epsilon(X^k)$, but

$$\begin{aligned}\Pi_y^\epsilon(X^k) &= (\cdot - y)^k \\ &= \sum_{0 \leq l \leq k} \binom{k}{l} (x - y)^{l-k} (\cdot - x)^k \\ &= \Pi_x^\epsilon \left(\sum_{0 \leq l \leq k} \binom{k}{l} (x - y)^{l-k} X^l \right).\end{aligned}$$

whence we set $\Gamma_{x,y}^\epsilon(X^k) = \sum_{0 \leq l \leq k} \binom{k}{l} (x - y)^{l-k} X^l$.

Example 1 (Noise)

Consider $\tau = \cdot$.

We want $\Pi_x^\epsilon(\Gamma_{x,y}^\epsilon(\cdot)) = \Pi_y^\epsilon(\cdot)$, but

$$\Pi_y^\epsilon(\cdot) = \xi_\epsilon = \Pi_x^\epsilon(\cdot)$$

whence we set $\Gamma_{x,y}^\epsilon(\cdot) = \cdot$.

Example 2 (Convolution)

Consider $\tau = \mathfrak{i}$.

We want $\Pi_x^\epsilon(\Gamma_{x,y}^\epsilon(\mathfrak{i})) = \Pi_y^\epsilon(\mathfrak{i})$ but

$$\begin{aligned}\Pi_y^\epsilon(\mathfrak{i}) &= K * \xi_\epsilon(\cdot) - K * \xi_\epsilon(y) \\ &= K * \xi_\epsilon(\cdot) - K * \xi_\epsilon(x) + K * \xi_\epsilon(x) - K * \xi_\epsilon(y) \\ &= \Pi_x^\epsilon(\mathfrak{i} + (K * \xi_\epsilon(x) - K * \xi_\epsilon(y))\mathbf{1}),\end{aligned}$$

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Example 3 (Product)

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whence we set $\Gamma_{x,y}^\epsilon(\mathbf{i}) = \mathbf{i} + (\mathbf{K} * \xi_\epsilon(x) - \mathbf{K} * \xi_\epsilon(y))\bullet$.

All calculations done, we can write explicitly:

$$\Gamma_{x,y}^\epsilon = \begin{matrix} j \backslash i & \cdot & \mathbf{1} & \cdot X_1 & \cdot X_2 & \mathbf{1} & \mathbf{1} & X_1 & X_2 \\ \cdot & 1 & K * \xi_\epsilon(x) - K * \xi_\epsilon(y) & x_1 - y_1 & x_2 - y_2 & 0 & 0 & 0 & 0 \\ \mathbf{1} & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ \cdot X_1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ \cdot X_2 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ \mathbf{1} & 0 & 0 & 0 & 0 & 1 & K * \xi_\epsilon(x) - K * \xi_\epsilon(y) & x_1 - y_1 & x_2 - y_2 \\ \mathbf{1} & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ X_1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ X_2 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{matrix},$$

Some first properties

The reexpansion operator Γ^ϵ

- is triangular with 1 on the diagonal;
- is Hölder continuous: $|\Gamma_{x,y}^{\sigma,\tau}| \lesssim |y - x|^{\alpha_\tau - \alpha_\sigma}$;
- satisfies the group property: $\Gamma_{x,y}^\epsilon \Gamma_{y,z}^\epsilon = \Gamma_{x,z}^\epsilon$.

Consequence: the pair $M^\epsilon = (\Pi^\epsilon, \Gamma^\epsilon)$ is a *model*.

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Multiplicativity of Γ

Note that for all (applicable) symbols τ, τ' ,

$$\Gamma_{x,y}^\epsilon(\tau\tau') = \Gamma_{x,y}^\epsilon(\tau)\Gamma_{x,y}^\epsilon(\tau').$$

Example:

$$\begin{aligned}\Gamma_{x,y}^\epsilon(\mathfrak{i}) &= \mathfrak{i} + (\mathsf{K} * \xi_\epsilon(x) - \mathsf{K} * \xi_\epsilon(y)) \bullet \\ &= (\mathfrak{i} + (\mathsf{K} * \xi_\epsilon(x) - \mathsf{K} * \xi_\epsilon(y)) \mathbb{1}) \bullet \\ &= \Gamma_{x,y}^\epsilon(\mathfrak{i}) \Gamma_{x,y}^\epsilon(\bullet).\end{aligned}$$

NB: Multiplicativity of Γ is guaranteed in general by the algebraic construction.

Admissibility of (Π, Γ)

The model M^ϵ satisfies:

$$\begin{aligned}\Pi_x^\epsilon(\mathfrak{i}) &= K * \Pi_x^\epsilon(\cdot)(\cdot) - K * \Pi_x^\epsilon(\cdot)(x), \\ \Gamma_{x,y}^\epsilon(\mathfrak{i}) &= \mathfrak{i} - \Pi_x^\epsilon(\mathfrak{i})(y)\mathbb{1}, \\ \Gamma_{x,y}^\epsilon(\tau\tau') &= \Gamma_{x,y}^\epsilon(\tau)\Gamma_{x,y}^\epsilon(\tau') \quad \tau, \tau' \in T.\end{aligned}$$

We say that M^ϵ is *admissible*, and note \mathcal{M}_{adm} the corresponding set.

(NB: In this condition, Γ is multiplicative but not necessarily Π .)

Consequence: for $M = (\Pi, \Gamma) \in \mathcal{M}_{\text{adm}}$, Γ is determined by Π i.e. we may identify M and Π .

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Stationarity of (Π, Γ)

For φ, h, τ , the random processes

$$x \mapsto \Pi_x^\epsilon(\tau)(\varphi_x), \quad x \mapsto \Gamma_{x, x+h}^\epsilon(\tau),$$

are stationary i.e. their distribution do not depend on x .

Example:

$$\begin{aligned}\Pi_x(\cdot)(\varphi_x) &= K * \xi_\epsilon(\varphi_x) - K * \xi_\epsilon(x) \\ &= \xi((K * \rho^\epsilon * \varphi - K * \rho^\epsilon)_x).\end{aligned}$$

Useful consequence: for all $x \in \mathbb{R}^d$,

$$\mathbb{E}[|\Pi_x^\epsilon(\tau)(\varphi_x^\lambda)|^2] = \mathbb{E}[|\Pi_0^\epsilon(\tau)(\varphi^\lambda)|^2].$$

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$d = 2$: the modelled distributions

Modelled distributions

We fix $M \in \mathcal{M}_{\text{adm}}$ an admissible model.

Definition (Modelled distributions)

The space \mathcal{D}^γ of modelled distributions for M is the space of functions $f(x) = \sum_{\tau} f_{\tau}(x)\tau$ with

$$|f_{\tau}(x)| \lesssim 1, \quad \left| f_{\tau}(x) - \sum_{\sigma} \Gamma_{x,y}^{\tau,\sigma} f_{\sigma}(y) \right| \lesssim |y - x|^{\gamma - \alpha_{\tau}}.$$

We will note $\|\cdot\|_{\mathcal{D}_K^\gamma}$ the corresponding seminorm on the compact K .

Then: the germ $F_x := \sum_{\tau} f_{\tau}(x)\Pi_x(\tau) =: \langle \Pi, f \rangle_x$, is (α, γ) -coherent for $\alpha = \min_{\tau}(\alpha_{\tau}) = -1 - \kappa$.

Iterating the equation: we want to set up the fixed-point in the subspace $\mathcal{D}_{\text{fp}}^\gamma$ of \mathcal{D}^γ of modelled distributions of the form

$$f(x) = a(x)\mathbb{1} + b(x)\mathfrak{I} + c_1(x)X_1 + c_2(x)X_2.$$

For the model M^ϵ , this corresponds to germs

$$\begin{aligned} F_x(\cdot) &= \Pi_x^\epsilon(f(x))(\cdot) \\ &= a(x) + b(x)(\mathbf{K} * \xi_\epsilon(\cdot) - \mathbf{K} * \xi_\epsilon(x)) \\ &\quad + c_1(x)(\cdot_1 - x_1) + c_2(x)(\cdot_2 - x_2). \end{aligned}$$

Multiplication operator

Theorem (Multiplication)

Let $f(x) = a(x)\mathbb{1} + b(x)\mathfrak{i} + c_1(x)X_1 + c_2(x)X_2$ be in $\mathcal{D}_{\text{fp}}^\gamma$ for some $\gamma > 1$. Set

$$f\cdot(x) := a(x)\cdot + b(x)\mathfrak{i}\cdot + c_1(x)\cdot X_1 + c_2(x)\cdot X_2.$$

Then $f\cdot \in \mathcal{D}^{\gamma-1-\kappa}$ with continuity bounds

$$\|f\cdot\|_{\mathcal{D}_K^{\gamma-1-\kappa}} = \|f\|_{\mathcal{D}_K^\gamma}.$$

NB: this is a particular case of a general multiplication result for modelled distributions, see [Hai14, Theorem 4.7].

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Convolution operator

Let K be the fundamental solution of the Laplacian.

Theorem (Multi-level Schauder estimates)

*There is an operator $\mathcal{K}: \mathcal{D}^\gamma \rightarrow \mathcal{D}^{\gamma+2}$ such that $\mathcal{R} \circ \mathcal{K} = K * \mathcal{R}$. Furthermore, \mathcal{K} is explicit in function of M and \mathcal{R} , with continuity bounds*

$$\|\mathcal{K}(f)\|_{\mathcal{D}_K^{\gamma+2}} \leq C \|\Pi\|_{\mathcal{M}_{K \oplus B(0,A)}} \|f\|_{\mathcal{D}_{K \oplus B(0,A)}^\gamma},$$

Theorem (Truncation of modelled distributions)

Let $f \in \mathcal{D}^\gamma$ and $\gamma' < \gamma$, then truncating f at level γ' gives a modelled distribution $f^{\leq \gamma'} \in \mathcal{D}^{\gamma'}$, with continuity bounds

$$\|f^{\leq \gamma'}\|_{\mathcal{D}_K^{\gamma'}} \leq C(1 + \|\Gamma\|_K) \|f\|_{\mathcal{D}_K^\gamma},$$

Fixed-point

Consequence: the operator

$$\begin{aligned}\mathcal{P}: \mathcal{D}_{\text{fp}}^\gamma &\rightarrow \mathcal{D}_{\text{fp}}^\gamma \\ f &\mapsto \mathcal{K}^{\gamma-1-\kappa}(\alpha \bullet + \beta f \bullet),\end{aligned}$$

is well defined, with continuity bounds

$$\|\mathcal{P}(f) - \mathcal{P}(g)\|_{\mathcal{D}_K^\gamma} \leq \beta C \left(1 + \|M\|_{\mathcal{M}_{K \oplus B(0,A)}}\right)^{k_0} \|f - g\|_{\mathcal{D}_{K \oplus B(0,A)}^\gamma},$$

Slight problem as in $d = 1$: the Lipschitz constant depends on the compact K .

Forgetting this technical difficulty: \mathcal{P} becomes a contraction for β small enough.

For the reconstruction $\phi_\epsilon := \mathcal{R}^\epsilon(f^\epsilon)$:

$$\phi_\epsilon = \mathcal{K} * ((\alpha + \beta \phi_\epsilon) \xi_\epsilon).$$

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Enhanced continuity

For the operations described above, there are “enhanced” continuity estimates: comparing modelled distributions over different models.

Consequence: there exists a continuous solution map

$$S: U \rightarrow \bigsqcup_{M \in \mathcal{M}_{\text{adm}}} \mathcal{D}_M^\gamma,$$

for some open set $U = U_\beta \subset \mathcal{M}_{\text{adm}}$, corresponding to the fixed-point above.

Question: does the (random) sequence $(M^\epsilon)_{\epsilon>0}$ converge in \mathcal{M}_{adm} ?

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$d = 2$: convergence of models

Kolmogorov's criterion for models

Theorem (“Kolmogorov's criterion for stationary models”)

Let $(M^\epsilon = (\Pi^\epsilon, \Gamma^\epsilon))_{\epsilon>0}$ be a sequence of stationary admissible models in \mathcal{M}_{adm} , defined on $(\Omega, \mathcal{F}, \mathbb{P})$.

Assume that there exist $\kappa, \theta > 0$ such that for all symbols τ of negative homogeneity, all test-functions φ , and all $p \geq 1$, $\epsilon, \epsilon_1, \epsilon_2 \in (0, 1)$,

$$\begin{aligned}\mathbb{E}[|\Pi_0^\epsilon(\tau)(\varphi^\lambda)|^p] &\leq C_{\tau, \varphi, p} \lambda^{p(\alpha_\tau + \kappa)}, \\ \mathbb{E}[|(\Pi_0^{\epsilon_1}(\tau) - \Pi_0^{\epsilon_2}(\tau))(\varphi^\lambda)|^p] &\leq C_{\tau, \varphi, p} (\epsilon_1 + \epsilon_2)^{p\theta} \lambda^{p(\alpha_\tau + \kappa)}.\end{aligned}$$

Then for all $p \geq 1$, the sequence $(M^\epsilon)_{\epsilon>0}$ converges in $L^p((\Omega, \mathcal{F}, \mathbb{P}); \mathcal{M}_{\text{adm}})$.

Proof: uses wavelets. See [Hai14, Theorem 10.7]

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Remark: gaussianity assumptions usually give equivalence of moments. In our case it will suffice to obtain the bounds only for $p = 2$:

$$\begin{aligned}\mathbb{E}[|\Pi_0^\epsilon(\tau)(\varphi^\lambda)|^2] &\leq C_{\tau,\varphi}\lambda^{2\alpha_\tau+\kappa}, \\ \mathbb{E}[|(\Pi_0^{\epsilon_1}(\tau) - \Pi_0^{\epsilon_2}(\tau))(\varphi^\lambda)|^2] &\leq C_{\tau,\varphi}(\epsilon_1 + \epsilon_2)^\theta\lambda^{2\alpha_\tau+\kappa}.\end{aligned}$$

In our case, the concerned symbols are

$$\tau \in \{\cdot, \cdot X_1, \cdot X_2, !\}.$$

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Example 1

Let us consider the symbol $\tau = \cdot$. By definition,

$$\Pi_0^\epsilon(\cdot)(\varphi^\lambda) = \xi_\epsilon(\varphi^\lambda) = \xi * \rho^\epsilon(\varphi^\lambda) = \xi(\rho^\epsilon * \varphi^\lambda).$$

So: $\mathbb{E}[|\Pi_0^\epsilon(\cdot)(\varphi^\lambda)|^2] = \|\rho^\epsilon * \varphi^\lambda\|_{L^2}^2$ (isometry of ξ).

Recall Young's convolution inequality in \mathbb{R}^d :

$$\|f * g\|_{L^r} \leq \|f\|_{L^p} \|g\|_{L^q}, \quad \text{if } \frac{1}{p} + \frac{1}{q} = \frac{1}{r} + 1, \quad 1 \leq p, q, r \leq +\infty.$$

Consequence:

$$\begin{aligned} \mathbb{E}[|\Pi_0^\epsilon(\cdot)(\varphi^\lambda)|^2] &\leq \|\rho^\epsilon\|_{L^1}^2 \|\varphi^\lambda\|_{L^2}^2 \quad (\text{Young}) \\ &= \|\rho\|_{L^1}^2 \|\varphi\|_{L^2}^2 \lambda^{-2}, \end{aligned}$$

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Example 1

The second bound concerns

$$\mathbb{E}[|(\Pi_0^{\epsilon_1}(\cdot) - \Pi_0^{\epsilon_2}(\cdot))(\varphi^\lambda)|^2] = \|(\rho^{\epsilon_1} - \rho^{\epsilon_2}) * \varphi^\lambda\|_{L^2}^2.$$

The function $\rho^{\epsilon_1, \epsilon_2} := \rho^{\epsilon_1} - \rho^{\epsilon_2}$ has vanishing integral:

$$\begin{aligned}\rho^{\epsilon_1, \epsilon_2} * \varphi^\lambda(x) &= \int \rho^{\epsilon_1, \epsilon_2}(z) \varphi^\lambda(x - z) dz \\ &= \int \rho^{\epsilon_1, \epsilon_2}(z) (\varphi^\lambda(x - z) - \varphi^\lambda(x)) dz.\end{aligned}$$

Consequence:

$$\|\rho^{\epsilon_1, \epsilon_2} * \varphi^\lambda\|_{L^2}^2 = \int \int \rho^{\epsilon_1, \epsilon_2}(z_1) \rho^{\epsilon_1, \epsilon_2}(z_2) F_\lambda(z_1, z_2) dz_1 dz_2,$$

for $F_\lambda(z_1, z_2) := \int (\varphi^\lambda(x - z_1) - \varphi^\lambda(x))(\varphi^\lambda(x - z_2) - \varphi^\lambda(x)) dx$.

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Change of variable:

$$F_\lambda(z_1, z_2) = \lambda^{-2} \int (\varphi(u - \frac{z_1}{\lambda}) - \varphi(u))(\varphi(u - \frac{z_2}{\lambda}) - \varphi(u)) du.$$

Since φ is θ -Hölder for any $\theta \in (0, 1)$:

$$|F_\lambda(z_1, z_2)| \leq C_{\theta, \varphi} \lambda^{-d} \left| \frac{z_1}{\lambda} \right|^\theta \left| \frac{z_2}{\lambda} \right|^\theta = C_{\theta, \varphi} \lambda^{-d-2\theta} |z_1|^\theta |z_2|^\theta.$$

This implies as wanted

$$\|(\rho^{\epsilon_1} - \rho^{\epsilon_2}) * \varphi^\lambda\|_{L^2}^2 \leq C_{\theta, \varphi, \rho} \lambda^{-2-2\theta} (\epsilon_1 + \epsilon_2)^{2\theta}.$$

Example 2

Let us consider $\tau = \cdot X_1$. By definition,

$$\Pi_0^\epsilon(\cdot X_1)(\varphi^\lambda) = \xi_\epsilon(\cdot_1 \varphi^\lambda(\cdot)) = \xi(\rho^\epsilon * (\cdot_1 \varphi^\lambda(\cdot))).$$

Define $\eta(\cdot) := \cdot_1 \varphi(\cdot)$. Then $\cdot_1 \varphi^\lambda(\cdot) = \lambda \eta^\lambda(\cdot)$, thus

$$\Pi_0^\epsilon(\cdot X_1)(\varphi^\lambda) = \lambda \Pi_0^\epsilon(\cdot)(\eta^\lambda).$$

Consequence: the estimates for $\cdot X_1$, $\cdot X_2$ follow from those for \cdot .

Example 3

It remains to consider $\tau = \mathbf{i}$. By definition,

$$\begin{aligned}\Pi_0^\epsilon(\mathbf{i})(\varphi^\lambda) &= \int (\mathbf{K} * \xi_\epsilon(x) - \mathbf{K} * \xi_\epsilon(0)) \xi_\epsilon(x) \varphi^\lambda(x) dx \\ &= \int \xi(\mathbf{K}_\epsilon(\cdot - x) - \mathbf{K}_\epsilon(\cdot)) \xi(\rho^\epsilon(\cdot - x)) \varphi^\lambda(x) dx\end{aligned}$$

This is less immediate to estimate. Useful tool: chaos decomposition.

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This is less immediate to estimate. Useful tool: chaos decomposition.

Chaos decomposition

Because ξ is gaussian white noise:

Fact (Wiener's isometry)

There exists an (explicit) linear map

$$I: \bigoplus_{n \geq 0} (L^2(\mathbb{R}^d))^{\otimes n} \rightarrow L^2(\Omega, \mathcal{F}, \mathbb{P}),$$

such that

- for $f \in L^2(\mathbb{R}^d)$, $I_1(f) = \xi(f)$;
- for $f, g \in L^2(\mathbb{R}^d)$, $I_2(f \otimes g) = I_1(f)I_1(g) - \langle f, g \rangle$ (NB: there is a general product formula);
- for $f \in (L^2(\mathbb{R}^d))^{\otimes n}$, $\mathbb{E}[|I_n(f)|^2] \leq n! \|f\|_{L^2}^2$.

Back to example 3

Now we can decompose:

$$\begin{aligned}\Pi_0^\epsilon(\cdot)(\varphi^\lambda) &= \int \xi(K_\epsilon(\cdot - x) - K_\epsilon(\cdot))\xi(\rho^\epsilon(\cdot - x))\varphi^\lambda(x)dx \\ &= \int I_1(K_\epsilon(\cdot - x) - K_\epsilon(\cdot))I_1(\rho^\epsilon(\cdot - x))\varphi^\lambda(x)dx \\ &= \int \left(I_2(K_\epsilon(\cdot - x) - K_\epsilon(\cdot) \otimes \rho^\epsilon(\cdot - x)) \right. \\ &\quad \left. + \langle K_\epsilon(\cdot - x) - K_\epsilon(\cdot), \rho^\epsilon(\cdot - x) \rangle \right) \varphi^\lambda(x)dx \\ &= I_2 \left(\int K_\epsilon(\cdot - x) - K_\epsilon(\cdot) \otimes \rho^\epsilon(\cdot - x) \varphi^\lambda(x)dx \right) \\ &\quad + \int \langle K_\epsilon(\cdot - x) - K_\epsilon(\cdot), \rho^\epsilon(\cdot - x) \rangle \varphi^\lambda(x)dx\end{aligned}$$

Back to example 3

We get the chaos decomposition:

$$\begin{aligned}\Pi_0^\epsilon(\varphi^\lambda) &= \langle K_\epsilon, \rho^\epsilon \rangle \int \varphi^\lambda(x) dx - \int K_\epsilon * \rho^\epsilon(x) \varphi^\lambda(x) dx \\ &\quad + I_2 \left(\int K_\epsilon(\cdot - x) - K_\epsilon(\cdot) \otimes \rho^\epsilon(\cdot - x) \varphi^\lambda(x) dx \right).\end{aligned}$$

We estimate the terms separately: recall $K(x) = -\frac{1}{2\pi} \log |x|$:

$$\begin{aligned}C_\epsilon &:= \langle K_\epsilon, \rho^\epsilon \rangle = \int \int K(\epsilon z) \rho(x - z) \rho(x) dx dz \\ &= - \int \int \frac{1}{2\pi} \log |\epsilon z| \rho(x - z) \rho(x) dx dz \\ &= -\frac{1}{2\pi} \log |\epsilon| + \text{cst}_\rho,\end{aligned}$$

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We get the chaos decomposition:

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For the second term, we exploit the singularity at origin of K :

$$|K(x)| \lesssim |x|^{-\kappa}.$$

This is preserved by mollification: $|K_\epsilon * \rho^\epsilon(x)| \lesssim |x|^{-\kappa}$. Thus:

$$\left| \int K_\epsilon * \rho^\epsilon(x) \varphi^\lambda(x) dx \right|^2 \lesssim \lambda^{-2\kappa}.$$

Back to example 3

We get the chaos decomposition:

$$\begin{aligned}\Pi_0^\epsilon(\varphi^\lambda) &= \langle K_\epsilon, \rho^\epsilon \rangle \int \varphi^\lambda(x) dx - \int K_\epsilon * \rho^\epsilon(x) \varphi^\lambda(x) dx \\ &\quad + I_2 \left(\int K_\epsilon(\cdot - x) - K_\epsilon(\cdot) \otimes \rho^\epsilon(\cdot - x) \varphi^\lambda(x) dx \right).\end{aligned}$$

For the third term, we use the isometry property of I :

$$\mathbb{E}[|I_2(\cdot)|^2] \lesssim \left\| \int K_\epsilon(\cdot - x) - K_\epsilon(\cdot) \otimes \rho^\epsilon(\cdot - x) \varphi^\lambda(x) dx \right\|_{L^2}^2.$$

This is “explicit” in function of K , ρ . Using again the singularity at origin this is $\lesssim \lambda^{-2\kappa}$.

Back to example 3

We get the chaos decomposition:

$$\begin{aligned}\Pi_0^\epsilon(\mathbf{i})(\varphi^\lambda) &= \langle K_\epsilon, \rho^\epsilon \rangle \int \varphi^\lambda(x) dx - \int K_\epsilon * \rho^\epsilon(x) \varphi^\lambda(x) dx \\ &\quad + I_2 \left(\int K_\epsilon(\cdot - x) - K_\epsilon(\cdot) \otimes \rho^\epsilon(\cdot - x) \varphi^\lambda(x) dx \right).\end{aligned}$$

Conclusion:

$$\Pi_0^\epsilon(\mathbf{i})(\varphi^\lambda) = \Pi_x^\epsilon(C_\epsilon \mathbf{1})(\varphi^\lambda) + \text{OK},$$

with $C_\epsilon = -\frac{1}{2\pi} \log |\epsilon| + O(1) \xrightarrow{\epsilon \rightarrow 0} \infty$.

$d = 2$: renormalisation

The conclusion of the previous section: if we consider the *renormalised model* \hat{M}^ϵ defined by

$$\hat{\Pi}_x^\epsilon(\tau) := \begin{cases} \Pi_x^\epsilon(\mathbf{i} - C_\epsilon \mathbf{1}) & \text{if } \tau = \mathbf{i}, \\ \Pi_x^\epsilon(\tau) & \text{else,} \end{cases} \quad \hat{\Gamma}^\epsilon = \Gamma^\epsilon,$$

with $C_\epsilon = -\frac{1}{2\pi} \log |\epsilon| + O(1)$ defined above, then $(\hat{M}^\epsilon)_{\epsilon>0}$ converges.

NB: By continuity of the solution map $\mathcal{M}_{\text{adm}} \rightarrow \mathcal{D}^\gamma$ and of the reconstruction operator $\mathcal{D}^\gamma \rightarrow \mathcal{D}'$, the sequence $\hat{\phi}_\epsilon := \hat{\mathcal{R}}^\epsilon(\hat{f}_\epsilon) \in \mathcal{D}'$ with

$$\hat{f}_\epsilon = \hat{\mathcal{K}}^\epsilon(\alpha_\bullet + \hat{f}_{\epsilon^\bullet}),$$

converges.

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$$\hat{f}_\epsilon = \hat{\mathcal{K}}^\epsilon(\alpha_\bullet + \hat{f}_{\epsilon\bullet}),$$

converges.

The renormalised model

Explicitly:

$$\hat{\Pi}_x^\epsilon(\cdot)(\cdot) = \xi_\epsilon(\cdot),$$

$$\hat{\Pi}_x^\epsilon(\mathfrak{!})(\cdot) = (\mathsf{K} * \xi_\epsilon(\cdot) - \mathsf{K} * \xi(x))\xi_\epsilon(\cdot) - C_\epsilon,$$

$$\hat{\Pi}_x^\epsilon(\cdot X_1)(\cdot) = \xi_\epsilon(\cdot)(\cdot_1 - x_1),$$

$$\hat{\Pi}_x^\epsilon(\cdot X_2)(\cdot) = \xi_\epsilon(\cdot)(\cdot_2 - x_2),$$

$$\hat{\Pi}_x^\epsilon(\mathbf{1})(\cdot) = 1,$$

$$\hat{\Pi}_x^\epsilon(\mathfrak{!})(\cdot) = \mathsf{K} * \xi_\epsilon(\cdot) - \mathsf{K} * \xi_\epsilon(x),$$

$$\hat{\Pi}_x^\epsilon(X_1)(\cdot) = \cdot_1 - x_1,$$

$$\hat{\Pi}_x^\epsilon(X_2)(\cdot) = \cdot_2 - x_2.$$

Some remarks

- $\hat{\Gamma}^\epsilon = \Gamma^\epsilon$: Π is not uniquely determined by Γ for admissible models;
- $\hat{\Gamma}^\epsilon = \Gamma^\epsilon$ is true in this case but not in general;
- $\hat{\Pi}^\epsilon$ is not multiplicative anymore: $\hat{\Pi}^\epsilon(\cdot \uparrow) \neq \hat{\Pi}^\epsilon(\uparrow)$.

The renormalised equations

Question: to what equation does the model $\hat{\Pi}^\epsilon$ correspond?
More precisely: let \hat{f}_ϵ be a modelled distribution with

$$\hat{f}_\epsilon = \hat{\mathcal{K}}^\epsilon(\alpha_\bullet + \hat{f}_\epsilon \bullet). \quad (50)$$

What equation does $\hat{\phi}_\epsilon := \hat{\mathcal{R}}^\epsilon(\hat{f}_\epsilon)$ satisfy?

First remark: by iterating (50):

$$\hat{f}_\epsilon(x) = a_\epsilon(x)\mathbb{1} + (\alpha + \beta a_\epsilon(x))\dagger + c_{1,\epsilon}(x)X_1 + c_{2,\epsilon}(x)X_2,$$

So:

$$\hat{\phi}_\epsilon(x) = \hat{\mathcal{R}}^\epsilon(\hat{f}_\epsilon)(x) = \hat{\Pi}_x^\epsilon(\hat{f}_\epsilon(x))(x) = a_\epsilon(x).$$

The renormalised equations

Question: to what equation does the model $\hat{\Pi}^\epsilon$ correspond?
More precisely: let \hat{f}_ϵ be a modelled distribution with

$$\hat{f}_\epsilon = \hat{\mathcal{K}}^\epsilon(\alpha_\bullet + \hat{f}_\epsilon)_\bullet.$$

What equation does $\hat{\phi}_\epsilon := \hat{\mathcal{R}}^\epsilon(\hat{f}_\epsilon)$ satisfy?

Second remark:

$$\hat{\phi}_\epsilon = \hat{\mathcal{R}}^\epsilon(\hat{f}_\epsilon) = \hat{\mathcal{R}}^\epsilon(\hat{\mathcal{K}}^\epsilon(\alpha_\bullet + \hat{f}_\epsilon)_\bullet) = \mathsf{K} * (\hat{\mathcal{R}}^\epsilon(\alpha_\bullet + \beta \hat{f}_\epsilon)_\bullet).$$

But $\hat{\Pi}^\epsilon$ is explicit:

$$\hat{\mathcal{R}}^\epsilon(\alpha_\bullet + \beta \hat{f}_\epsilon)_\bullet(x) = \hat{\Pi}_x^\epsilon(\alpha_\bullet + \beta \hat{f}_\epsilon(x)_\bullet)(x) = (\alpha + \beta \hat{\phi}_\epsilon(x))(\xi_\epsilon(x) - \beta C_\epsilon).$$

The renormalised equations

Question: to what equation does the model $\hat{\Pi}^\epsilon$ correspond?
More precisely: let \hat{f}_ϵ be a modelled distribution with

$$\hat{f}_\epsilon = \hat{\mathcal{K}}^\epsilon(\alpha_\bullet + \hat{f}_\epsilon \bullet).$$

What equation does $\hat{\phi}_\epsilon := \hat{\mathcal{R}}^\epsilon(\hat{f}_\epsilon)$ satisfy?

Conclusion: $\hat{\phi}_\epsilon$ solves

$$\hat{\phi}_\epsilon = \mathbf{K} * ((\alpha + \beta \hat{\phi}_\epsilon(x))(\xi_\epsilon(x) - \beta C_\epsilon)).$$

Family of solutions

NB: we can replace C_ϵ by $C_\epsilon + c$ for any constant $c \in \mathbb{R}$ and still obtain convergence.

This gives a whole family of solutions indexed by \mathbb{R} .

Thank you for your attention!

