

VII taller de análisis no lineal y ecuaciones  
diferenciales parciales

28 al 31 de mayo 2025 - UTP

*On the Navier-Stokes equations for stationary  
incompressible fluids with a discontinuous density  
and the Ladyzhenskaya-Solonnikov problem for  
the power model*

# Overview

- ▶ Discontinuous density in a bounded domain of the plane
- ▶ Variable viscosity
- ▶ Leray problem
- ▶ Ladyzhenskaya-Solonnikov problem

# The stationary Navier-Stokes equations for incompressible inhomogeneous fluids

$$\begin{cases} -\nu \Delta \mathbf{v} + \rho(\mathbf{v} \cdot \nabla) \mathbf{v} + \nabla \mathcal{P} = \rho \mathbf{f} \\ \operatorname{div}(\mathbf{v}) = 0, \quad \operatorname{div}(\rho \mathbf{v}) = 0 \end{cases} \quad (1)$$

$\rho$  : density  
 $\mathbf{v}$  : velocity  
( $\mathcal{P}$  : pressure) } the unknowns

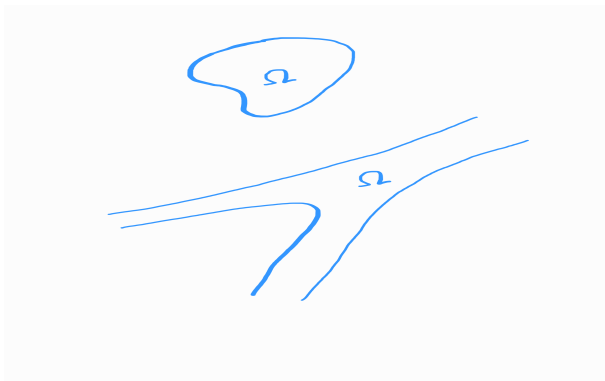
$\mathbf{f}$  : external force

$\nu > 0$  : constant viscosity

$$\mathbf{v} = (v_1, \dots, v_n), \quad (\mathbf{v} \cdot \nabla) \mathbf{v} = (\mathbf{v} \cdot \nabla v_1, \dots, \mathbf{v} \cdot \nabla v_n)$$

# Domains

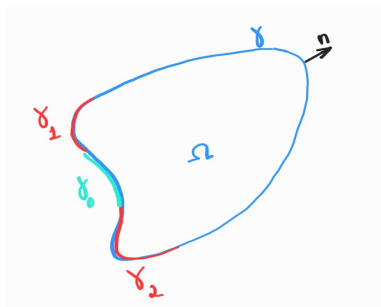
We consider these equations (system (1)) in a bounded domain and in an unbounded domain (a domain with an unbounded boundary)



## The bounded domain

The bounded domain we consider only in 2D (in the plane) with the boundary being a Jordan curve  $\gamma$  (i.e., a smooth simple closed curve).

We take three successive arcs on  $\gamma$ ,  $\gamma_1$ ,  $\gamma_0$ ,  $\gamma_2$ , denote by  $\mathbf{n}$  the unit outward normal on  $\gamma$



and pose the following boundary value problem:

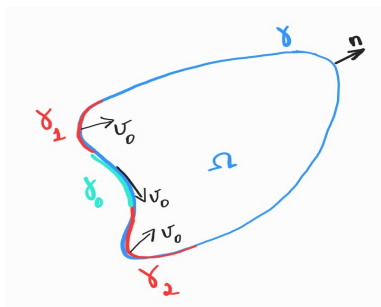
## Boundary value problem (bvp) in the bounded domain

$$\left\{ \begin{array}{l} -\nu \Delta \mathbf{v} + \rho(\mathbf{v} \cdot \nabla) \mathbf{v} + \nabla P = \rho \mathbf{f} \\ \operatorname{div}(\mathbf{v}) = 0, \quad \operatorname{div}(\rho \mathbf{v}) = 0 \\ \mathbf{v}|_{\gamma} = \mathbf{v}_0, \quad \rho|_{\gamma_i} = \rho_i, \quad i = 1, 2 \end{array} \right\} \quad \text{in } \Omega \quad (2)$$

where  $\mathbf{v}_0$  or the set  $\{\gamma_1, \gamma_0, \gamma_2\}$  is such that

$$\gamma_1 \cup \gamma_2 = \{x \in \gamma; \mathbf{v}_0 \cdot \mathbf{n} < 0\},$$

and  $\mathbf{v}_0 \cdot \mathbf{n} = 0$  on



$\gamma_1 \cup \gamma_2$  is the part of  $\gamma$  where the fluid is incoming.

(Compatibility condition:  $\int_{\gamma} \mathbf{v}_0 \cdot \mathbf{n} = 0$ .)

## Theorem (–, ZAMP, 2002)

If  $\rho_i \in L^\infty(\gamma_i)$ ,  $i = 1, 2$ ,  $\mathbf{f} \in L^2(\Omega)$  and  $\mathbf{v}_0 \in H^{1/2}(\gamma)$  satisfies  $(\mathbf{v}_0 \cdot \mathbf{n})|_{\gamma_i} < 0$ ,  $i = 1, 2$ ,  $(\mathbf{v}_0 \cdot \mathbf{n})|_{\gamma_0} = 0$  and  $\int_\gamma \mathbf{v}_0 \cdot \mathbf{n} = 0$ , then problem (2) has a weak solution\*  $(\rho, \mathbf{v})$  in  $L^\infty(\Omega) \times H^1(\Omega)$ .

\*

### Definition

A pair  $(\rho, \mathbf{v}) \in L^\infty(\Omega) \times H^1(\Omega)$  is said to be a *weak solution* of problem (1) if  $\operatorname{div}(\mathbf{v}) = 0$  in  $H^1(\Omega)$  (i.e.  $\int_\Omega \mathbf{v} \cdot \nabla \theta \, dx = 0$  for all  $\theta \in C_0^\infty(\Omega)$ ),  $\mathbf{v}|_\gamma = \mathbf{v}_0$  where  $\mathbf{v}|_\gamma$  is the trace of  $\mathbf{v}$  on  $\gamma$ ,

$$\int_\Omega \rho \mathbf{v} \cdot \nabla \varphi \, dx = \int_{\gamma_i} \rho_i (\mathbf{v}_0 \cdot \mathbf{n}) \varphi \, ds, \quad (3)$$

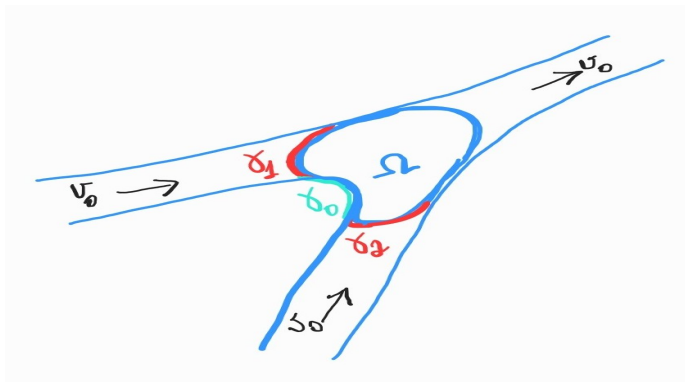
for all  $\varphi \in H^1(\Omega)$  such that  $\varphi|_{(\gamma/\gamma_i)} = 0$ ,  $i = 1, 2$ , and

$$\nu \int_\Omega \nabla v_j \cdot \nabla \Phi_j \, dx - \int_\Omega \rho v_j \mathbf{v} \cdot \frac{\partial \Phi}{\partial x_j} \, dx = \int_\Omega \rho \mathbf{f} \cdot \Phi \, dx, \quad (4)$$

for all  $\Phi = (\Phi_1, \Phi_2) \in C_0^\infty(\Omega; \mathbb{R}^2)$  such that  $\operatorname{div}(\Phi) = 0$ .

# Physical motivation

The meeting of fluids, e.g., the junction of rivers with different densities



## On the proof

N.N. Frolov (in Mat. Zametki, 1993) solved the problem (2) in the case that

$$\gamma_1 = \{x \in \gamma; \mathbf{v}_0 \cdot \mathbf{n} < 0\},$$

( $\gamma_2 = \emptyset$ ) and  $\rho_1$  is a Hölder continuous function.

In particular, he proved the existence of a solution  $(\rho, \mathbf{v})$  in  $C^\alpha(\Omega) \times H^2(\Omega)$ , if  $\mathbf{v}_0 \in C^2(\gamma)$ ,  $\rho_1 \in C^\alpha(\gamma_1)$  and  $\mathbf{f} \in L^2(\Omega)$  ( $\alpha > 0$ ).

## Frolov method

- Since  $\operatorname{div}(\mathbf{v}) = 0$  and  $\Omega$  is simply connected, we can write

$$\mathbf{v} = \nabla^\perp \psi := \left( -\frac{\partial \psi}{\partial x_2}, \frac{\partial \psi}{\partial x_1} \right)$$

for some scalar function  $\psi$  (*stream function*). Frolov looks for solutions with  $\rho$  in the form  $\rho = \omega(\psi) \equiv \omega \circ \psi$ , for a smooth function  $\omega : \mathbb{R} \rightarrow \mathbb{R}$ . Note that such a  $\rho$  automatically satisfies the equation  $\operatorname{div}(\rho \mathbf{v}) = 0$ .

$$(\operatorname{div}(\rho \mathbf{v}) = \nabla \rho \cdot \mathbf{v} = \omega'(\psi) \nabla \psi \cdot \nabla^\perp \psi = 0)$$

- The boundary condition  $\rho|_{\gamma_i} = \rho_i$  imposes the following restriction on  $\omega$ :

$$\omega(\psi(x)) = \rho_i(x), \quad x \in \gamma_i. \tag{5}$$

## The bvp for $\psi$

If  $(\rho, \mathbf{v})$  is smooth, we may take the curl of the first equation in (1) and easily see that the problem (1) turns into the following boundary value problem for the unknown  $\psi$ :

$$\begin{cases} \nu \Delta^2 \psi = -\operatorname{div}(\omega(\psi)(\nabla^\perp \psi \cdot \nabla) \nabla \psi) + \operatorname{div}(\omega(\psi) \mathbf{f}^\perp) & \text{in } \Omega, \\ \frac{\partial \psi}{\partial \tau} = -\mathbf{v}_0 \cdot \mathbf{n}, \quad \frac{\partial \psi}{\partial \mathbf{n}} = \mathbf{v}_0 \cdot \boldsymbol{\tau} & \text{on } \gamma, \end{cases} \quad (6)$$

where  $\mathbf{f}^\perp = (-f_2, f_1)$ ,  $\mathbf{f} = (f_1, f_2)$ ,  $\boldsymbol{\tau} = \mathbf{n}^\perp$ .

Notice that  $\operatorname{curl} \mathbf{f} = \frac{\partial f_2}{\partial x_1} - \frac{\partial f_1}{\partial x_2} = -\operatorname{div} \mathbf{f}^\perp$ ,  $\operatorname{curl} \nabla^\perp \psi = \Delta \psi$ , and  $((\mathbf{v} \cdot \nabla) \mathbf{v})^\perp = (\mathbf{v} \cdot \nabla) \mathbf{v}^\perp$ .

## Solving the bvp (6)

The idea is to use the *Leray-Schauder fixed point theorem*\*:

Let  $V$  be a Banach space, and let  $\mathcal{A} : [0, 1] \times V \rightarrow V$  be a map such that  $\mathcal{A}(0, \cdot)$  is a constant map. Suppose that

i.  $\mathcal{A}$  is continuous and compact, and

ii. the set  $\mathcal{S} = \{v \in V : \mathcal{A}(\mu, v) = v \text{ for some } \mu \in [0, 1]\}$  is bounded.

Then the map  $\mathcal{A}(1, \cdot)$  has a fixed point.

## Solving the bvp (6) – the extension of boundary values

First we define

$$\psi_0 = - \int_{\gamma} \mathbf{v}_0 \cdot \mathbf{n} \quad (7)$$

and fix  $\omega : \mathbb{R} \rightarrow \mathbb{R}$  such that

Second, by a converse of the *trace theorem*<sup>†</sup>, we can take a function  $\widetilde{\Phi}_0$  defined in  $\overline{\Omega}$  such that

$$\widetilde{\Phi}_0|_{\gamma} = \psi_0, \quad \frac{\partial \widetilde{\Phi}_0}{\partial \mathbf{n}}|_{\gamma} = \mathbf{v}_0 \cdot \boldsymbol{\tau} \quad (8)$$

and

$$\|\widetilde{\Phi}_0\|_{H^2(\Omega)} \leq c(\|\psi_0\|_{H^{3/2}(\gamma)} + \|\mathbf{v}_0\|_{H^{1/2}(\gamma)}), \quad (9)$$

where  $c$  is a constant depending only on  $\Omega$ .

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<sup>†</sup>see e.g. Theorem 3.4, p. 48 in G. P. Galdi, *An Introduction to the Mathematical Theory of the Navier-Stokes Equations*, v. I, Springer (1994)

## Solving the bvp (6) – the extension of boundary values, continued

Finally, we take the following family of extensions of  $\psi_0$  to  $\Omega$ , concentrating the support of  $\widetilde{\Phi}_0$  and controlling its “slope” near the boundary  $\gamma$ :

$$\widetilde{\psi}_{0,\delta} := \widetilde{\Phi}_0 \zeta_\delta, \quad 0 < \delta \ll 1$$

that is,  $\zeta_\delta$  is a smooth function such that  $\zeta_\delta = 1$  near  $\gamma$ , zero at all points of  $\Omega$  with distance from  $\gamma$  bigger than  $\delta$  and

$$|\zeta_\delta(x)| \leq c, \quad |\nabla \zeta_\delta(x)| \leq c/\delta, \quad (10)$$

where  $c$  is a constant independent of  $x$  and

The arbitrariness of  $0 < \delta \ll 1$  above is important!

## Solving the bvp (6) – the homogenization of boundary values and the variational problem

Let us consider a solution of (6) given by  $\psi = \varphi + \widetilde{\psi}_{0,\delta}$ , where  $\varphi$  is now the unknown we seek in the space  $H_0^2(\Omega)$ .

Multiplying the equations in (6) by test functions  $\theta \in H_0^2(\Omega)$  and integrating by parts we see that  $\varphi$  satisfies the following variational problem:

$$\begin{aligned} & \nu \int_{\Omega} (\Delta\varphi)(\Delta\theta) \, dx \\ = & \int_{\Omega} \omega(\varphi + \widetilde{\psi}_{0,\delta}) \left( \nabla^\perp(\varphi + \widetilde{\psi}_{0,\delta}) \right)_j \left( \nabla^\perp(\varphi + \widetilde{\psi}_{0,\delta}) \right) \cdot \frac{\partial}{\partial x_j} (\nabla^\perp\theta) \, dx \\ & + \int_{\Omega} \omega(\varphi + \widetilde{\psi}_{0,\delta}) \mathbf{f} \cdot (\nabla^\perp\theta) \, dx - \nu \int_{\Omega} (\Delta\widetilde{\psi}_{0,\delta})(\Delta\theta) \, dx. \end{aligned} \tag{11}$$

Solving the bvp (6) – the solution as a fixed point of the map associated with the right hand side of (11)

$$\mathcal{A} : [0, \nu^{-1}] \times H_0^2(\Omega) \longrightarrow H_0^2(\Omega)$$

$$\begin{aligned} (\mathcal{A}(\mu, \varphi), \theta) := & \\ & \mu \int_{\Omega} \omega(\mu\nu\tilde{\psi}_{0,\delta} + \varphi) \left( \nabla^\perp(\mu\nu\tilde{\psi}_{0,\delta} + \varphi) \right)_j \nabla^\perp(\mu\nu\tilde{\psi}_{0,\delta} + \varphi) \cdot \frac{\partial}{\partial x_j}(\nabla^\perp\theta) \\ & + \mu \int_{\Omega} \omega(\mu\nu\tilde{\psi}_{0,\delta} + \varphi) \mathbf{f} \cdot (\nabla^\perp\theta) dx - \mu\nu \int_{\Omega} (\Delta\tilde{\psi}_{0,\delta})(\Delta\theta) dx, \end{aligned} \tag{12}$$

where we endowed  $H_0^2(\Omega)$  with the inner product

$$(\varphi, \theta) := \int_{\Omega} (\Delta\varphi)(\Delta\theta) dx.$$

A fixed point of  $\mathcal{A}(\nu^{-1}, \cdot)$  is a solution of (11).

The existence of a fixed point of  $\mathcal{A}(\nu^{-1}, \cdot)$  is guaranteed by the Leray-Schauder fixed point theorem because the two following claims hold true.

i.  $\mathcal{A}$  is continuous and compact.

ii. The set

$\mathcal{S} := \{\varphi \in H_0^2(\Omega) : \mathcal{A}(\mu, \varphi) = \varphi \text{ for some } \mu \in [0, \nu^{-1}]\}$  is a bounded set in  $H_0^2(\Omega)$ .

The proof of claim i. uses the Hölder continuity of  $\Omega$ . In fact, assuming  $\omega \in C^\alpha(\mathbb{R})$ , Frolov (in Mat. Zametki, 1993) obtains the estimates

$$\|\mathcal{A}(\mu_1, \varphi_1) - \mathcal{A}(\mu_1, \varphi_2)\|_{H^2} \leq c \|\varphi_1 - \varphi_2\|_{W^{1,4}}^\alpha \quad (13)$$

and

$$\|\mathcal{A}(\mu_1, \varphi_1) - \mathcal{A}(\mu_2, \varphi_1)\|_{H^2} \leq c |\mu_1 - \mu_2|^\alpha \quad (14)$$

for all  $\varphi_1, \varphi_2$  in an arbitrary ball  $B$  of  $H^2(\Omega)$  and  $\mu_1, \mu_2 \in [0, \nu^{-1}]$ , where  $c$  is a constant that depends only on  $\omega$ ,  $\delta$ ,  $B$  and Sobolev imbeddings. From (13) and (14) it follows claim i.

## On the proof of claim ii.

For claim ii, it suffices that  $\omega$  be continuous and bounded.

The arbitrariness of  $\delta$  is used here!

In fact, assuming that the set  $\mathcal{S}$  is not bounded for some  $0 < \delta_1 \ll 1$ , following an argument in the book by Ladyzhenskaya<sup>‡</sup>, it is possible to find some limit function  $\mathbf{z} \in H_0^2(\Omega)$  independent of  $\delta \in (0, \delta_1]$  such that

$$\begin{aligned} \nu \leq & c \|\omega\|_{L^\infty(\mathbb{R})} \|\widetilde{\Phi}_0\|_{L^\infty(\Omega)} (\delta^{-1} \|\mathbf{z}\|_{L^2(\Omega_\delta)}) \\ & + c \|\omega\|_{L^\infty(\mathbb{R})} \|\nabla^\perp \widetilde{\Phi}_0\|_{L^4(\Omega_\delta)} \|\mathbf{z}\|_{L^4(\Omega_\delta)}, \end{aligned} \quad (15)$$

for all  $\delta \in (0, \delta_1]$ . This leads to a contradiction when letting  $\delta \rightarrow 0$ , since  $\nu > 0$  and, by a Poincaré type inequality, we have that  $\delta^{-1} \|\mathbf{z}\|_{L^2(\Omega_\delta)} \leq c_1 \|\mathbf{z}\|_{H^1(\Omega_\delta)}$ , where  $c_1$  is some constant independent of  $\delta$ . This ends the proof of claim ii.

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<sup>‡</sup>O. A. Ladyzhenskaya, *The Mathematical Theory of Viscous Incompressible Flow*, (1969), p. 123

## Frolov's theorem (Mat. Zametki, 1993)

Given any bounded and Hölder continuous function  $\omega : \mathbb{R} \rightarrow \mathbb{R}$ , if  $\mathbf{f} \in L^2(\Omega)$  and  $\mathbf{v}_0 \in C^2(\gamma)$  then, for each  $0 < \delta \ll 1$ , the bvp (6), i.e.,

$$\begin{cases} \nu \Delta^2 \psi = -\operatorname{div}(\omega(\psi)(\nabla^\perp \psi \cdot \nabla) \nabla \psi) + \operatorname{div}(\omega(\psi) \mathbf{f}^\perp) & \text{in } \Omega, \\ \frac{\partial \psi}{\partial \tau} = -\mathbf{v}_0 \cdot \mathbf{n}, \quad \frac{\partial \psi}{\partial \mathbf{n}} = \mathbf{v}_0 \cdot \boldsymbol{\tau} & \text{on } \gamma, \end{cases}$$

has a weak solution  $\psi$  of the type  $\psi = \varphi + \widetilde{\psi}_{0,\delta}$ , with  $\varphi \in H_0^2(\Omega)$ .

## On the proof of our theorem (in ZAMP, 2002)

If  $\rho_i \in L^\infty(\gamma_i)$ ,  $i = 1, 2$ ,  $\mathbf{f} \in L^2(\Omega)$  and  $\mathbf{v}_0 \in H^{1/2}(\gamma)$  satisfies  $(\mathbf{v}_0 \cdot \mathbf{n})|_{\gamma_i} < 0$ ,  $i = 1, 2$ ,  $(\mathbf{v}_0 \cdot \mathbf{n})|_{\gamma_0} = 0$  and  $\int_\gamma \mathbf{v}_0 \cdot \mathbf{n} = 0$ , then problem (2) has a weak solution  $(\rho, \mathbf{v})$  in  $L^\infty(\Omega) \times H^1(\Omega)$ .

We approximate all data, use Frolov's theorem and pass to the limit.

- Data approximations:

$$\begin{aligned}\gamma_i^\epsilon &:= (\inf \gamma_i + \epsilon, \sup \gamma_i - \epsilon), \quad i = 1, 2, & 0 < \epsilon \ll 1 \\ (\mathbf{v}_0^\epsilon \cdot \boldsymbol{\tau})(\lambda(s)) &:= (((\mathbf{v}_0 \cdot \boldsymbol{\tau}) \circ \lambda^{per}) * m^\epsilon)(s) \\ (\mathbf{v}_0^\epsilon \cdot \mathbf{n})(\lambda(s)) &:= (((\mathbf{v}_0 \cdot \mathbf{n}) \circ \lambda^{per}) * m^\epsilon)(s) \\ \mathbf{v}_0^\epsilon &:= (\mathbf{v}_0^\epsilon \cdot \boldsymbol{\tau})\boldsymbol{\tau} + (\mathbf{v}_0^\epsilon \cdot \mathbf{n})\mathbf{n} \\ \rho_0^\epsilon(\lambda(s)) &:= ((\rho_0 \circ \lambda^{per}) * m^\epsilon)(s) \\ \rho_i^\epsilon &:= \rho_0^\epsilon|_{\gamma_i^\epsilon}\end{aligned}$$

where

## Notations in the data approximations

$\lambda : [0, \ell) \rightarrow \mathbb{R}^2$ ,  $\ell > 0$ , is a smooth parametrization of  $\gamma$  with  $\lambda'(s) = \tau(\lambda(s))$  (we recall that  $\tau := \mathbf{n}^\perp$ );

$\lambda^{per}$  is the periodical extension of  $\lambda$  to  $\mathbb{R}$  of  $\lambda$  with period  $\ell$ ;

$*$  stands for the convolution in  $\mathbb{R}$ ;

$\rho_0$  is the extension to  $\gamma$  of  $\rho_1$  and  $\rho_2$  defined by setting  $\rho_0(x) = \rho_i(x)$  for  $x \in \gamma_i$ ,  $i = 1, 2$ , and  $\rho_0(x) = 0$  for  $x \in \gamma / (\gamma_1 \cup \gamma_2)$  and;

$\{m^\epsilon\}$  is a sequence of mollifiers in  $\mathbb{R}$ , i.e.,  $m^\epsilon(s) = \epsilon^{-1}\phi(s/\epsilon)$  for some even function  $\phi : \mathbb{R} \rightarrow [0, \infty)$  such that  $\text{supp } \phi \subset [-1, 1]$  and  $\int_{\mathbb{R}} \phi = 1$ .

## Approximate solution

For  $\omega^\epsilon : \mathbb{R} \rightarrow \mathbb{R}$  being a smooth and bounded function such that  $\omega^\epsilon(\psi_0^\epsilon | \gamma_i^\epsilon) = \rho_i^\epsilon$ , where  $\psi_0^\epsilon := - \int_\gamma (\mathbf{v}_0^\epsilon \cdot \mathbf{n})$ , and  $0 < \delta \ll 1$ , using Frolov's theorem we take a solution of the type  $\psi^\epsilon = \varphi^\epsilon + \widetilde{\psi}_{0,\delta}^\epsilon$  of the bvp

$$\begin{cases} \nu \Delta^2 \psi^\epsilon = -\operatorname{div}(\omega^\epsilon(\psi^\epsilon)(\nabla^\perp \psi^\epsilon \cdot \nabla) \nabla \psi^\epsilon) + \operatorname{div}(\omega(\psi^\epsilon)(\mathbf{f}^\epsilon)^\perp) & \text{in } \Omega, \\ \frac{\partial \psi^\epsilon}{\partial \tau} = -\mathbf{v}_0^\epsilon \cdot \mathbf{n}, \quad \frac{\partial \psi^\epsilon}{\partial \mathbf{n}} = \mathbf{v}_0^\epsilon \cdot \boldsymbol{\tau} & \text{on } \gamma, \end{cases} \quad (16)$$

where  $\mathbf{f}^\epsilon$  is smooth and converges to  $\mathbf{f}$  in  $L^2(\Omega)$  (when  $\epsilon \rightarrow 0$ ).

Approximate solution to the bvp (2):

$$(\rho^\epsilon, \mathbf{v}^\epsilon) := (\omega^\epsilon(\psi^\epsilon), \nabla^\perp \psi^\epsilon).$$

- Convergence of  $(\rho^\epsilon, \mathbf{v}^\epsilon)$ : [–, ZAMP 2002, section 3].

## Variable viscosity

$$\begin{cases} -\operatorname{div}(\nu D(\mathbf{v})) + \rho(\mathbf{v} \cdot \nabla)\mathbf{v} + \nabla\mathcal{P} = \rho\mathbf{f} \\ \operatorname{div}(\mathbf{v}) = 0, \quad \operatorname{div}(\rho\mathbf{v}) = 0 \end{cases} \quad (17)$$

where  $D(\mathbf{v})$  is the symmetric part of velocity gradient  $\nabla\mathbf{v}$ , i.e.,

$$D(\mathbf{v}) = \frac{1}{2}(\nabla\mathbf{v} + (\nabla\mathbf{v})^t)$$

(we notice that  $\operatorname{div}(D(\mathbf{v})) = \Delta\mathbf{v}$ ).

Two cases:

$$\nu = \mu(\rho) \quad \nu = |D(\mathbf{v})|^{p-2}$$

# The case $\nu = \mu(\rho)$

Theorem (• He, Zihui. Doctoral dissertation, Karlsruhe Institut für Technologie (KIT), Germany, (2022); • He, Zihui, and Liao, Xian. Communications in Contemporary Mathematics, (2024).)

Let  $\mu, \omega : \mathbb{R} \rightarrow \mathbb{R}$  be bounded and continuous functions, with  $\mu \geq \mu_*$  for some constant  $\mu_* > 0$ . If  $\mathbf{f} \in L^2(\Omega)$  and  $\mathbf{v}_0 \in H^{1/2}(\gamma)$  satisfies  $\int_{\gamma} \mathbf{v}_0 \cdot \mathbf{n} = 0$  then the bvp

$$\left\{ \begin{array}{l} -\operatorname{div}(\mu(\rho)D(\mathbf{v})) + \rho(\mathbf{v} \cdot \nabla)\mathbf{v} + \nabla\mathcal{P} = \mathbf{f} \\ \operatorname{div}(\mathbf{v}) = 0, \quad \operatorname{div}(\rho\mathbf{v}) = 0 \\ \mathbf{v}|_{\gamma} = \mathbf{v}_0 \end{array} \right\} \quad \text{in } \Omega \quad (18)$$

has a weak solution  $(\rho, \mathbf{v})$  of the form  $(\rho, \mathbf{v}) = (\omega(\psi), \nabla^{\perp}\psi)$ , where  $\psi = \varphi + \widetilde{\psi}_{0,\delta}$ , with  $\varphi \in H_0^2(\Omega)$ , is a solution of the bvb below.

## Zihui-Liao's theorem, continued – Bvp for $\psi$ :

$$\begin{cases} L_\mu \psi = -\operatorname{div}(\omega(\psi)(\nabla^\perp \psi \cdot \nabla) \nabla \psi) + \operatorname{div}(\omega(\psi) \mathbf{f}^\perp) & \text{in } \Omega, \\ \frac{\partial \psi}{\partial \tau} = -\mathbf{v}_0 \cdot \mathbf{n}, \quad \frac{\partial \psi}{\partial \mathbf{n}} = \mathbf{v}_0 \cdot \boldsymbol{\tau} & \text{on } \gamma, \end{cases} \quad (19)$$

where  $L_\mu$  is the following fourth order elliptic operator:

$$L_\mu = \nabla^\perp \cdot \operatorname{div}(\mu D) = (\partial_{x_2 x_2} - \partial_{x_1 x_1}) \mu (\partial_{x_2 x_2} - \partial_{x_1 x_1}) + (2\partial_{x_1 x_2}) \mu (2\partial_{x_1 x_2}).$$

# Leray problem

The stationary Navier-Stokes equations for incompressible fluids (with constant density  $\rho = 1$  and without external force, i.e.,  $\mathbf{f} = \mathbf{0}$ )

$$\begin{cases} -\nu \Delta \mathbf{v} + (\mathbf{v} \cdot \nabla) \mathbf{v} + \nabla \mathcal{P} = \mathbf{0} \\ \operatorname{div}(\mathbf{v}) = 0 \end{cases} \quad (20)$$

## Domain with an unbounded boundary for Leray problem (Domain with straight channels/outlets to infinity)

Let  $\Omega$  be a open connect set set in  $\mathbb{R}^n$  ( $n = 2, 3$ ) with a  $C^\infty$  boundary, such that

$$\Omega = \bigcup_{i=0}^2 \Omega_i ,$$

where  $\Omega_0$  is a bounded subset of  $\mathbb{R}^n$  and, in possibly different Cartesian coordinate system,

$$\Omega_1 = \{x = (x', \bar{x}) \in \mathbb{R}^n; x' < 0, |\bar{x}| < d_1\}$$

and

$$\Omega_2 = \{x = (x', \bar{x}) \in \mathbb{R}^n; x' > 0, |\bar{x}| < d_2\},$$

with  $d_i > 0$ ,  $i = 1, 2$ .

We denote by  $\mathbf{n}$  the unit orthonormal vector to any cross section of  $\Omega$ , pointing from  $\Omega_1$  toward  $\Omega_2$ .

## Poiseuille flow

Let  $\mathbf{v} \equiv \mathbf{v}_P$  of the form

$$\mathbf{v}_P(x) = v_P(\bar{x})\vec{e}$$

(a parallel velocity field) be a solution of (20) in a straight unbounded cylinder

$$C = \{ (x', \bar{x}) \equiv (x'\vec{e}) \oplus \bar{x}; -\infty < x' < \infty, \bar{x} \in \Sigma, \},$$

where  $\Sigma$  is a connect and simply connect open set in  $\mathbb{R}^{n-1}$  independent of  $x'$ , such that  $v_P|_{\partial\Sigma} = 0$ .

Then

$$\begin{cases} -\Delta v_P = c & \text{in } \Sigma \\ v_P = 0 & \text{on } \partial\Sigma. \end{cases} \quad (21)$$

for some constant  $c$ .

The vector field  $\mathbf{v}_P$  is called *Poiseuille flow*.

## Poiseuille flow, continued

The constant  $c$  can be determined by the flux  $\Phi := \int_{\Sigma} v_P$ .

Indeed, if  $v_1$  is the solution corresponding to  $c = 1$  then  $v_P = cv_1$ , thus, multiplying the first equation in (21) by  $v_P$  and integrating by parts in  $\Sigma$ , with the help of the boundary condition  $v_P|_{\partial\Sigma} = 0$ , we obtain that

$$c\Phi = \int_{\Sigma} cv_P = - \int_{\Sigma} (\Delta v_P)v_P = \int_{\Sigma} |\nabla v_P|^2 = c^2 \int_{\Sigma} |\nabla v_1|^2.$$

With this computation, we also have that

$$\int_{\Sigma} |\nabla v_P|^2 = c\Phi = \Phi^2 / \int_{\Sigma} |\nabla v_1|^2, \text{ i.e.,}$$

$$\int_{\Sigma} |\nabla v_P|^2 = c_1 \Phi^2,$$

where  $c_1$  is the constant given by  $c_1 = 1 / \int_{\Sigma} |\nabla v_1|^2$  and depends only on the cross section  $\Sigma$  of the cylinder  $C$ .

We also notice that  $\int_{\Sigma} |\nabla v_1|^2 = - \int_{\Sigma} (\Delta \nabla v_1)v_1 = \int_{\Sigma} v_1 =: \Phi_1$ , the flux of the vector field  $v_1$  over  $\Sigma$ . In particular, we also can write

$$c_1 = 1/\Phi_1.$$

## Remark

Using the divergence theorem, it is easy to prove that the flux  $\int_{\Sigma} \mathbf{v} \cdot \mathbf{n}$  of a vector field  $\mathbf{v}$  over a cross section  $\Sigma$  of  $\Omega$ , such that  $\operatorname{div} \mathbf{v} = 0$  in  $\Omega$  and  $\mathbf{v}|_{\partial\Omega} = 0$ , is independent of the cross section  $\Sigma$ .

# The Leray problem

Let  $\mathbf{v}_P^1 = v_P^1 \mathbf{n}$  be the Poiseuille flow in  $\Omega_1$  and  $\mathbf{v}_P^2 = v_P^2 \mathbf{n}$  the Poiseuille flow in  $\Omega_2$  with equal fluxes. Find a solution  $\mathbf{v}$  of (20) in  $\Omega$  such that  $\mathbf{v}|_{\partial\Omega} = 0$  and

$$\mathbf{v} \rightarrow \mathbf{v}_P^i \text{ as } |x'| \rightarrow \infty \text{ in } \Omega_i.$$

## Theorem (Amick, 1977)

Leray problem has a solution when the fluxes of the Poiseuille flow  $\mathbf{v}_P^i$  are sufficiently small.

Arbitrary flux: open question.

# Amick's solution of Leray's problem for Newtonian fluids, with small flux

$$\mathbf{v} = \mathbf{u} + \mathbf{a}; \quad \mathbf{u} \in H_0^1(\Omega), \quad \operatorname{div} \mathbf{u} = 0, \quad \operatorname{div} \mathbf{a} = 0, \\ \mathbf{a}|_{\Omega_i} = \mathbf{v}_P^i, \quad \mathbf{a} \in H_{\text{loc}}^1(\Omega), \quad \mathbf{a}|_{\partial\Omega} = 0.$$

Notice that the Poiseuille flows  $\mathbf{v}_P^i$  are not in  $H^1(\Omega)$  (they are constant with respect to  $x'$ );  $\mathbf{v}_P^i \in H_{\text{loc}}^1(\Omega)$ .

A divergence free vector field  $\mathbf{u}$  in  $H_0^1(\Omega) = \overline{C_c^\infty(\Omega)}^{H^1(\Omega)}$  carries no flux, i.e.,  $\int_{\Sigma} \mathbf{u} \cdot \mathbf{n} = 0$ , for any cross section  $\Sigma$  of  $\Omega$ . Indeed, if  $\psi \in C_c^\infty(\Omega)$  then  $\int_{\Sigma(x')} \psi \cdot \mathbf{n} = 0$  for all sufficiently large  $|x'|$ .

NS-equations become

$$-\Delta \mathbf{u} + \mathbf{u} \nabla \mathbf{u} + f(\mathbf{u}) + \nabla \mathcal{P} = 0,$$

where

$$f(\mathbf{u}) = \mathbf{a} \nabla \mathbf{u} + \mathbf{u} \nabla \mathbf{a} + \mathbf{a} \nabla \mathbf{a} - \Delta \mathbf{a}.$$

Method: compactness method, with Galerkin approximations.

Control of the nonlinear term  $\int (\mathbf{a}\nabla\mathbf{u})\mathbf{u}$  by  $\int |\nabla\mathbf{u}|^2$   
(a priori estimate)

$$\int |(\mathbf{a}\nabla\mathbf{u})\mathbf{u}| \leq (\int |\nabla\mathbf{u}|^2)^{1/2} (\int |\mathbf{a}|^2 |\mathbf{u}|^2)^{1/2}$$

$$\begin{aligned} \int_{\Omega_i} |\mathbf{a}|^2 |\mathbf{u}|^2 &= \int_{\Omega_i} |\mathbf{u}|^2 |\mathbf{v}_P^i|^2 \\ &= \left| \int_0^{\pm\infty} \int_{\Sigma} |\mathbf{v}_P^i|^2 |\mathbf{u}|^2 \right| \\ &\leq \left| \int_0^{\pm\infty} (\int_{\Sigma} |\mathbf{v}_P^i|^4)^{1/2} (\int_{\Sigma} |\mathbf{u}|^4)^{1/2} \right| \\ &= \left| \int_0^{\pm\infty} \|\mathbf{v}_P^i\|_{L^4(\Sigma)}^2 \|\mathbf{u}\|_{L^4(\Sigma)}^2 \right| \\ &\leq c \left| \int_0^{\pm\infty} \|\nabla\mathbf{v}_P^i\|_{L^2(\Sigma)}^2 \|\nabla\mathbf{u}\|_{L^2(\Sigma)}^2 \right| \\ &= c \|\nabla\mathbf{v}_P^i\|_{L^2(\Sigma)}^2 \left| \int_0^{\pm\infty} \|\nabla\mathbf{u}\|_{L^2(\Sigma)}^2 \right| \\ &= c\Phi^2 \int_{\Omega_i} |\nabla\mathbf{u}|^2 \end{aligned}$$

Similarly, we can estimate  $\int (\mathbf{u}\nabla\mathbf{a})\mathbf{u}$ .

The terms  $\int_{\Omega_i} (-\Delta\mathbf{a})\mathbf{u}$  and  $\int_{\Omega_i} (\mathbf{a}\nabla\mathbf{a})\mathbf{u}$  vanish, since  $\mathbf{a}\nabla\mathbf{a} = 0$ , because  $\mathbf{a} = v_P^i$  in  $\Omega_i$  is “parallel”, and  $-\Delta\mathbf{a} = (-\Delta\mathbf{v}_P^i)\mathbf{n} = c\mathbf{n}$  in  $\Omega_i$ , so

$$\int_{\Omega_i} (-\Delta\mathbf{a})\mathbf{u} = |c \int_0^{\pm\infty} \int_{\Sigma} \mathbf{u} \cdot \mathbf{n}| = 0.$$

## Leray problem for inhomogeneous fluid in 2D

—, F. Ammar-Khodja

Let  $\mathbf{v}_P^i$ ,  $i = 1, 2$ , be the Poiseuille flows as above and  $\rho_1$  be a given function in  $C_b(\Sigma_1)$  (the continuous case) or in  $L^\infty(\Sigma_1)$  (the discontinuous case), where  $\Sigma_1 = (-d_1, d_1)$ . Find a solution  $(\rho, \mathbf{v})$  of the system

$$\begin{cases} -\nu \Delta \mathbf{v} + \rho(\mathbf{v} \cdot \nabla) \mathbf{v} + \nabla \mathcal{P} = 0 \\ \operatorname{div}(\mathbf{v}) = 0, \quad \operatorname{div}(\rho \mathbf{v}) = 0 \end{cases} \quad (22)$$

in  $\Omega$  such that  $\mathbf{v}|_{\partial\Omega} = 0$ ,  $\lim_{(-1)^i x' \rightarrow \infty} \mathbf{v} = \mathbf{v}_P^i$  and

$$\lim_{x' \rightarrow -\infty} \rho = \rho_1.$$

## Theorem (—, F. Ammar-Khodja (2004, 2006))

The above problem has a weak solution  $(\rho, \mathbf{v})$  with  $\mathbf{v} \in H_{loc}^1(\bar{(\Omega)})$ ,  
 $\lim_{(-1)^i x \rightarrow \infty} \|\mathbf{v}(x, \cdot) - \mathbf{v}_P^i\|_{C_b(\Sigma_i)} = 0$ ,  $i = 1, 2$ , and:

$$\rho \in C_b(\Omega), \quad \lim_{x \rightarrow -\infty} \|\rho(x, \cdot) - \rho_1\|_{C_b(\Sigma_1)} = 0,$$

in the continuous case;

$$\rho \in L^\infty(\Omega), \quad * - \lim_{x \rightarrow -\infty, a.e.} \rho(x, \cdot) = \rho_1,$$

in the discontinuous case, where  $* - \lim_{x \rightarrow -\infty, a.e.}$  denotes the limit in the weak-\* topology of  $L^\infty(\Sigma_1)$ , with  $x$  tending to  $-\infty$  except for a set of zero Lebesgue measure.

# Ladyzhenskaya-Solonnikov problem

## Domain with unbounded channels containing straight cylinders

Let  $\Omega$  be a open connect set set in  $\mathbb{R}^n$  ( $n = 2, 3$ ) with a  $C^\infty$  boundary, such that

$$\Omega = \bigcup_{i=0}^2 \Omega_i ,$$

where  $\Omega_0$  is a bounded subset of  $\mathbb{R}^n$  and, in possibly different Cartesian coordinate system,

$$\Omega_1 = \{x = (\bar{x}, x') \in \mathbb{R}^n; x' < 0, \bar{x} \in \Sigma_1(x')\}$$

and

$$\Omega_2 = \{x = (\bar{x}, x') \in \mathbb{R}^n; x' > 0, \bar{x} \in \Sigma_2(x')\},$$

with  $\Sigma_i(x')$ ,  $i = 1, 2$ , being  $C^\infty$  simply connected domains in  $\mathbb{R}^{n-1}$  such that  $\sup_{x', i=1,2} \text{diam } \Sigma_i(x') < \infty$  and  $\Omega_i$ ,  $i = 1, 2$ , contains some cylinder

$$C_l^i = \{x \in \mathbb{R}^n; (-1)^i x' > 0 \text{ e } |\bar{x}| < l\}, \quad (l > 0)$$

(in particular,  $\inf_{x', i=1,2} \text{diam } \Sigma_i(x') > 0$ ).

We will denote by  $\mathbf{n}$  the unit orthonormal vector to  $\Sigma(x')$ , or to any cross section of  $\Omega$ , pointing from  $\Omega_1$  toward  $\Omega_2$ .

# The Ladyzhenskaya-Solonnikov problem

Given any  $\Phi \in \mathbb{R}$ , find a solution  $\mathbf{v}$  of the system

$$\begin{cases} -\nu \Delta \mathbf{v} + (\mathbf{v} \cdot \nabla) \mathbf{v} + \nabla \mathcal{P} = 0 \\ \operatorname{div}(\mathbf{v}) = 0 \end{cases}$$

in  $\Omega$  such that  $\mathbf{v}|_{\partial\Omega} = 0$ ,  $\int_{\Sigma(x')} \mathbf{v} \cdot \mathbf{n} = \Phi$  and

$$\sup_{t>0} t^{-1} \int_{\Omega^t} |\nabla \mathbf{v}|^2 < \infty,$$

where  $\Omega^t := \Omega_0 \cup \Omega_1^t \cup \Omega_2^t$ ,  $\Omega_i^t := \{(\bar{x}, x') \in \Omega_i; 0 < (-1)^i x' < t\}$ ,  
 $i = 1, 2$ .

“Problem 1.1” in

[LS] O.A. Ladyzhenskaya and V.A. Solonnikov, *Determination of the Solutions of Boundary Value Problems for Steady-State Stokes and Navier-Stokes Equations in Domains Having an Unbounded Dirichlet Integral* (1980). English transl. in J. Soviet Math. **21** (1983).

## Theorem (Ladyzhenskaya-Solonnikov, 1980)

*Given any flux ( $\Phi \in \mathbb{R}$ ), the above problem has a solution.*

Ladyzhenskaya-Solonnikov's solution, for Newtonian fluids with arbitrary flux:  $v = u + a$ ;  $u \in H_{loc}^1(\Omega)$ ,  $\operatorname{div} u = 0$ ,  $u|_{\partial\Omega} = 0$

and  $a$  is given by the following lemma:

**Lemma [LS].** *For any  $\delta > 0$  there exists a vector field  $a$  such that*

a<sub>1</sub>)  $a \in H_{loc}^1(\Omega)$ ,  $\operatorname{div} a = 0$ ,  $a|_{\partial\Omega} = 0$ ,

a<sub>2</sub>)  $\int_{\Sigma} a \cdot \mathbf{n} = 1$  for any cross section  $\Sigma$  of  $\Omega$ ,

a<sub>3</sub>)  $\int_{\Omega_i^{t-1,t}} |\nabla a|^2 \leq c$  for  $i = 1, 2$  and all  $t \geq 1$ , where

$$\Omega_i^{t-1,t} = \{(\bar{x}, x') \in \Omega_i; t-1 < |x'| < t\},$$

and

a<sub>4</sub>)  $\int_{\Omega_t} |a|^2 |u|^2 \leq c\delta \int_{\Omega_t} |\nabla u|^2$  for all  $t > 0$  and  $u \in C_c^\infty(\Omega)$ ,

where, in a<sub>3</sub>) and a<sub>4</sub>),  $c$  is a constant depending only on  $\Omega$ .

Remark: Given any  $\Phi \in \mathbb{R}$ , multiplying  $a$  by  $\Phi$ , we obtain a vector field having flux  $\Phi$ .

Now  $a|_{\Omega_i}$  might not be the Poiseuille  $v_p^i$ , but the compactness method still works, by truncating the domain and long computations:

Let  $u^t$  be a solution of the NS-equations

$$-\Delta u^t + u^t \nabla u^t + f(u^t) + \nabla \mathcal{P}^t = 0$$

in  $H_0^1(\Omega^t)$  (joint with some pressure function  $\mathcal{P}^t \in L_{loc}^2(\Omega^t)$ ).

Now, let  $t' > t$ . Multiplying the equation

$-\Delta u^{t'} + u^{t'} \nabla u^{t'} + f(u^{t'}) + \nabla \mathcal{P}^{t'} = 0$  by  $u^t$  and integrating by parts in  $\Omega^t$  ... [LS]

$$\int_{\Omega^t} |\nabla u^{t'}|^2 \leq ct + \int_{\Sigma(t)} (\text{bound. terms}),$$

for all  $t < t'$ . Integrating in  $t$ , from  $\eta - 1$  to  $\eta \leq t'$ , we get

$$z(\eta) := \int_{\eta-1}^{\eta} \left( \int_{\Omega^t} |\nabla u^{t'}|^2 \right) dt \leq c\eta - \frac{1}{4} + \int_{\Omega^{\eta-1, \eta}} (\text{bound. terms}).$$

Using the equation, is possible to estimate  $\int_{\Omega^{\eta-1, \eta}} (\text{bound. terms})$  by a linear combinations of powers of  $\int_{\Omega^{\eta-1, \eta}} |\nabla u^{t'}|^2$ . But

$$\int_{\Omega^{\eta-1, \eta}} |\nabla u^{t'}|^2 = z'(\eta)!$$

Thus,

$$z(\eta) := \int_{\eta-1}^{\eta} \left( \int_{\Omega^t} |\nabla u^{t'}|^2 \right) dt \leq c\eta + g(z'(\eta)), \quad \forall \eta \leq t',$$

for some function  $g: \mathbb{R} \rightarrow \mathbb{R}$ . Besides,

$$z(t') \leq \int_{\Omega^{t'}} |\nabla u^{t'}|^2 \leq ct'.$$

Then, by a kind of “reverse Gronwall lemma” [LS], we have

$$z(\eta) \leq c\eta,$$

which implies

$$\int_{\Omega^{\eta-1}} |\nabla u^{t'}|^2 \leq c\eta, \quad \forall \eta \leq t'.$$

So, fixing  $t$  (arbitrary),  $\{u^{t'}\}_{t' > t}$  is bounded in  $H^1(\Omega^t)$ , by  $c(t+1)$ .

Construction of  $a$ , in  $\Omega_j$  and with  $n = 3$ :

$$a = \frac{1}{2\pi} \nabla \times (\zeta b) = \frac{1}{2\pi} \nabla \zeta \times b,$$

where

$$b(x) = \left( -\frac{x_2}{|\bar{x}|^2}, \frac{x_1}{|\bar{x}|^2}, 0 \right), \quad \bar{x} = (x_1, x_2),$$

(the angle form in  $\Sigma$ ) and  $\zeta$  is the “truncating E. Hopf’s function”:

$$\zeta(x) = \psi \left( \varepsilon \log \frac{\sigma(|\bar{x}|)}{\rho(x)} \right);$$

$\rho(x)$ : the regularized distance to  $\partial\Omega$   
 $\sigma, \psi : \mathbb{R} \rightarrow \mathbb{R}$ : smooth nondecreasing functions,

$$\sigma(s) = \begin{cases} \frac{1}{4}, & s \leq \frac{1}{4} \\ t, & s > \frac{1}{2} \end{cases}$$

$$\psi(s) = \begin{cases} 0, & s \leq 0 \\ 1, & s > 1 \end{cases}$$

$\varepsilon = \varepsilon(\delta)$ .

The power model,  $\nu = |D(\mathbf{v})|^{p-2}$

The equations:

$$\left\{ \begin{array}{l} -\operatorname{div}(|D(\mathbf{v})|^{p-2}D(\mathbf{v})) + \nu\nabla\mathbf{v} + \nabla\mathcal{P} = 0 \\ \operatorname{div}\mathbf{v} = 0 \end{array} \right. \quad \text{power-law fluids}$$

$|D(\mathbf{v})|^{p-2}D(\mathbf{v})$  : viscous stress tensor,  $\mathbb{S}$ .

$\mathbb{S} = |D(\mathbf{v})|^{p-2}D(\mathbf{v})$  or viscosity =  $|D(\mathbf{v})|^{p-2}$

is the *power law* or *Ostwald-de Waele law (model)* for viscosity (1920s); see e.g. R. Bird, W. Stewart and E. Lightfoot, *Transport Phenomena*, John Wiley & Sons, Inc. (2007).

In the classical book by O. Ladyzhenskaya, *The Mathematical Theory of Viscous Incompressible Flow*, 2nd ed. (1969), after the last chapter, there is a description of some models including power laws.

$|D(v)|$ : shear rate

$p = 2$ : Newtonian fluids (e.g. water, oil)

$p < 2$ : *shear-thinning* (or plastic and pseudo-plastic, e.g. most polymer melts and solutions)

- viscosity decreases with the shear rate

$p > 2$ : *shear-thickening* (or dilatant, e.g. mud, clay, cement)

- viscosity increases with the shear rate

Cf. E. Marusic-Paloka, *Steady Flow of a Non-Newtonian Fluid in Unbounded Channels and Pipes*, Mathematical Models and Methods in Applied Sciences, **10**(9) (2000).

For **parallel fluids**,  $v(x) \equiv v(\bar{x})\vec{e}$ ,  $x = (\bar{x}, x') \equiv \bar{x} \oplus x'\vec{e}$ , the velocity field is given by a scalar function  $v(\bar{x})$ , the convection term  $v\nabla v$  vanishes, and the Navier-Stokes equations become the *p-Laplacian equation*

$$-\operatorname{div}(|\nabla v|^{p-2}\nabla v) = c$$

for some constant  $c$ , related to “pressure drop”, i.e.  $\nabla \mathcal{P} = -c\vec{e}$ .

## The domain

Let  $\Omega$  be a open connect set set in  $\mathbb{R}^n$ ,  $n = 2, 3$ , with a  $C^\infty$  boundary, such that

$$\Omega = \bigcup_{i=0}^2 \Omega_i,$$

where  $\Omega_0$  is a bounded subset of  $\mathbb{R}^n$  and, in possibly different Cartesian coordinate system,

$$\Omega_1 = \{x = (\bar{x}, x') \in \mathbb{R}^n; x' < 0, \bar{x} \in \Sigma_1(x')\}$$

and

$$\Omega_2 = \{x = (\bar{x}, x') \in \mathbb{R}^n; x' > 0, \bar{x} \in \Sigma_2(x')\},$$

with  $\Sigma_i(x')$ ,  $i = 1, 2$ , being  $C^\infty$  simply connected domains in  $\mathbb{R}^{n-1}$  such that

$$\sup_{x', i=1,2} \text{diam } \Sigma_i(x') < \infty$$

and  $\Omega_i$ ,  $i = 1, 2$ , contains some cylinder

$$C_l^i = \{x \in \mathbb{R}^n; (-1)^i x' > 0 \text{ e } |\bar{x}| < l\}, \quad (l > 0)$$

(in particular,  $\inf_{x', i=1,2} \text{diam } \Sigma_i(x') > 0$ ).

We will denote by  $\mathbf{n}$  the ortonormal vector to  $\Sigma(x')$ , or to any cross section of  $\Omega$ , pointing from  $\Omega_1$  toward  $\Omega_2$ .

## The problem

“Ladyzhenskaya-Solonnikov problem”

Given any  $\Phi \in \mathbb{R}$ , find a solution  $(v, \mathcal{P})$  of  $(NS)$  such that

$$v = 0 \quad \text{on } \partial\Omega,$$
$$\int_{\Sigma(x')} v \cdot \mathbf{n} = \Phi$$

and

$$\sup_{t>0} t^{-1} \int_{\Omega^t} |\nabla v|^p < \infty,$$

where  $\Omega^t := \Omega_0 \cup \Omega_1^t \cup \Omega_2^t$ ,  $\Omega_i^t := \{(\bar{x}, x') \in \Omega_i; 0 < (-1)^i x' < t\}$ ,  
 $i = 1, 2$ .

Cf. “Problem 1.1” in

**[LS]** O.A. Ladyzhenskaya and V.A. Solonnikov, *Determination of the Solutions of Boundary Value Problems for Steady-State Stokes and Navier-Stokes Equations in Domains Having an Unbounded Dirichlet Integral* (1980). English transl. in J. Soviet Math. **21** (1983).

## Theorem (—, G. Dias. Jr. Diff. Eq. (2012))

Let  $p \geq 2$  and  $n = 3$ . Then the Ladyzhesnkaya-Solonnikov problem for power-law fluids has a weak solution, i.e. there is a  $(v, \mathcal{P})$  in  $W_{loc}^{1,p}(\Omega) \times L_{loc}^{p'}(\Omega)$  such that







$$\left\{ \begin{array}{l} \int_{\Omega} |D(v)|^{p-2} D(v) : \nabla \psi = - \int_{\Omega} (v \nabla v) \cdot \psi + \int_{\Omega} \mathcal{P} \operatorname{div} \psi, \\ \forall \psi \in C_c^{\infty}(\Omega; \mathbb{R}^3) \\ \int_{\Omega} v \cdot \nabla \psi = 0, \quad \forall \psi \in C_c^{\infty}(\Omega; \mathbb{R}) \end{array} \right.$$

$$v|_{\partial\Omega} = 0, \quad \int_{\Sigma} v \cdot \mathbf{n} = \Phi$$








and

$$\sup_{t>0} t^{-1} \int_{\Omega^t} |\nabla v|^p < \infty.$$

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**Thank you all for your attention!**