

# Tube structures with forms defined on closed manifolds

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# Summary

The system under study

Statement when  $M$  is a surface

Global solutions

Final remarks

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Let  $c$  be a smooth closed 1-form defined on a closed manifold  $M$ .  
We consider the operator  $\mathbb{L} : C^\infty(M \times \mathbb{S}^1) \rightarrow C^\infty(M \times \mathbb{S}^1, \Lambda^{(1,0)})$ :

$$\mathbb{L}u = d_t u + c(t) \wedge \partial_x u.$$

Assuming that  $(t_1, \dots, t_n)$  are local coordinates on  $M$  and  $C$  a local primitive of  $c$ , we have the vector fields

$$L_j = \frac{\partial}{\partial t_j} + \frac{\partial C}{\partial t_j}(t) \frac{\partial}{\partial x}, \quad j = 1, \dots, n.$$

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They are local generators of  $\mathcal{V} \doteq (T')^\perp \subset \mathbb{C} \otimes T(M \times \mathbb{S}^1)$  where  $T'$  is the line sub-bundle of  $\mathbb{C} \otimes T^*(M \times \mathbb{S}^1)$  generated by the 1-form  $dx - c$ . Any involutive structure defines in a natural way a complex of differential operators - which in the case of  $\mathcal{V}$  is given by  $\mathbb{L}$  when acting on distributions:

$$\begin{aligned} \mathcal{D}'(M \times \mathbb{S}^1) &\xrightarrow{\mathbb{L}} \mathcal{U}^1(M \times \mathbb{S}^1) \xrightarrow{\mathbb{L}^1} \\ &\xrightarrow{\mathbb{L}^1} \mathcal{U}^2(M \times \mathbb{S}^1) \xrightarrow{\mathbb{L}^2} \dots \xrightarrow{\mathbb{L}^{n-1}} \mathcal{U}^n(M \times \mathbb{S}^1) \xrightarrow{\mathbb{L}^n} 0. \end{aligned}$$

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We study the smooth global solvability of  $\mathbb{L}$ , i.e., the possibility of finding a globally defined solution  $u \in \mathcal{D}'(M \times \mathbb{S}^1)$  to

$$\mathbb{L}u = d_t u + c(t) \wedge \partial_x u = f,$$

when  $f$  is smooth.

If  $f$  is in the range of  $\mathbb{L}$  it must satisfy:

- (i)  $\mathbb{L}f = 0$  (a consequence of the complex property  $\mathbb{L} \circ \mathbb{L} = 0$ );
- (ii)  $f$  must be orthogonal to the kernel of the adjoint operator  $\mathbb{L}^*$ .

While (i) is of local nature, the homology of  $M$  plays a role in (ii).



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They are usually referred to as the compatibility conditions for  $f$  (we write  $f \in \mathbb{E}$ ) and are formulated in several equivalent ways.

We say that the operator  $\mathbb{L}$  is globally hypoelliptic if

$$\mathbb{L}u \in C^\infty(M \times \mathbb{S}^1, \Lambda^{(1,0)}) \implies u \in C^\infty(M \times \mathbb{S}^1).$$

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## Statement when $c$ is exact

When  $c$  is smooth and exact, we can define a primitive of  $b$  on  $M$  by  $B(t) = \int_{t_0}^t b$ . In [Cardoso; Hounie, 1977] the authors characterized the global solvability as follows:

### Theorem

If  $b$  is exact the following statements are equivalent:

- (I)  $\mathbb{L}$  is globally solvable.
- (II) The semilevel sets  $\{t \in M : B(t) < r\}$  and  $\{t \in M : B(t) > r\}$  are connected for every  $r \in \mathbb{R}$ .

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# Minimal covering space

- We are given a manifold  $M$  where a real smooth closed 1-form  $b$  is defined.
- We construct a special covering space  $\tilde{M}$  on which a primitive  $\tilde{B}$  of  $b$  is defined.
- Call  $D$  the group of deck transformations of  $\tilde{M}$ .
- The primitive  $\tilde{B}$  is such that

$$\tilde{B}(\sigma(t)) - \tilde{B}(t) = b_\sigma,$$

for  $\sigma \in D$ , and  $b_\sigma = 0 \Leftrightarrow \sigma = 1$ .



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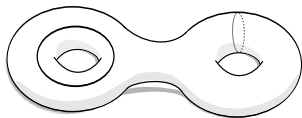
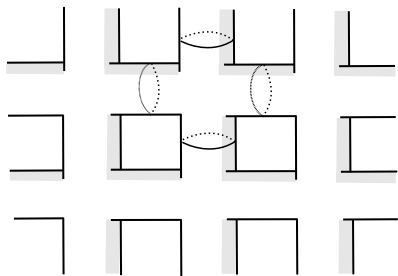
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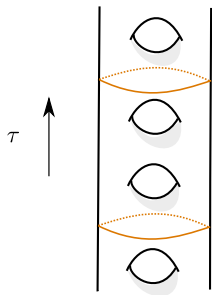
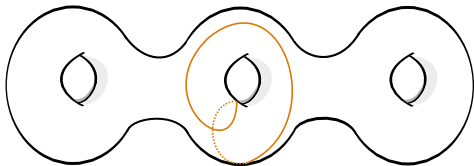
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Cutting where the periods are zero

$$\int_{\gamma_k} b = c_k, \int_{\delta_k} b = d_k, \text{ and } pc_k + qd_k = 0$$



$$B(\tau(t)) = B(t) + d'$$

$$B(t) = P(t) + d't_3$$

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- Denote by  $\mathcal{A}$  the set of the connected components  $\mathcal{O}$  of regular semilevel sets of  $\tilde{B}$  such that  $\tilde{B}$  is bounded on  $\mathcal{O}$ . Then consider the inclusion  $j : \mathcal{O} \hookrightarrow \tilde{M}$ .
- We will associate to  $\mathcal{O} \in \mathcal{A}$  the vector  $I(\mathcal{O}) = (\int_{\alpha_1} a, \dots, \int_{\alpha_\mu} a)$ , where  $\{\alpha_1, \dots, \alpha_\mu\}$  is a basis of the free part of  $j^* H_1(\mathcal{O}, \mathbb{Z})$ .

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## Theorem [Hounie; Zugliani, 2021]

Assume that  $M$  is a closed surface and that the 1-form  $c = a + ib$  is smooth and closed. The following statements are equivalent:

- (I)  $\mathbb{L}$  is globally solvable.
- (II) One of the conditions below is satisfied:
  - $\mathcal{A} = \emptyset$  or, if  $\mathcal{O} \in \mathcal{A}$ ,  $I(\mathcal{O})$  is neither a rational nor a Liouville vector.
  - $b$  is exact, the semilevel sets of  $\tilde{B}$  are connected;  $a$  is rational, and, if  $q \in \mathbb{Z}$  is such that  $qI(\mathcal{O}) \in (2\pi\mathbb{Z})^\mu$  for  $\mathcal{O} \in \mathcal{A}$ , then  $qa$  is integral.

# Compatibility conditions

## Definition

We say that a 1-form  $f \in C^\infty(M \times \mathbb{S}^1, \Lambda^{1,0})$  belongs to  $\mathbb{E}$  if:

- for each  $\xi \in \mathbb{Z}$  and each smooth curve  $\gamma$  connecting  $t$  to  $\sigma(t)$  in  $\mathcal{U}$  with  $i\xi c_\sigma \in 2\pi\mathbb{Z}$ ,

$$\int_{\gamma} e^{i\xi C(s)} \hat{f}(s, \xi) = 0.$$

- $d_t(e^{i\xi C(t)} \hat{f}(t, \xi)) = 0$  for every  $\xi \in \mathbb{Z}$ .

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- One can compute the Fourier coefficients of a candidate to a problem's solution on  $\tilde{M}$  by solving a differential equation for each  $\xi \in \mathbb{Z}$ , which yields

$$\hat{u}(t, \xi) = \int_{t_0}^t v + K_\xi e^{\xi C(t)},$$

where  $v = e^{i\xi[C(s)-C(t)]} \hat{f}(s, \xi)$ .

- Imposing the periodicity in order to define a solution on the manifold, we determine  $K_\xi$  and the coefficients, namely

$$\hat{u}(t, \xi) = \frac{1}{e^{\xi(i a_\sigma - b_\sigma)} - 1} \int_t^{\sigma(t)} v,$$

where  $C(\sigma(t)) - C(t) = c_\sigma = a_\sigma + i b_\sigma$ .

- We wish to prove that  $\{\hat{u}(t, \xi)\}$  decays rapidly.

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Regarding the proof of (II)  $\implies$  (I)

If  $a \equiv 0$ , we will have the desired control for  $\xi > 0$  if along the curve

$$B(s) \geq B(t) + \frac{1}{1 + |\xi|},$$

holds true, since

$$\hat{u}(t, \xi) = C_\xi \int_t^{t+(2\pi, 0)} \underbrace{e^{-\xi[B(s)-B(t)]}}_{\leq e^{-\xi \cdot \frac{1}{1+|\xi|}}} \underbrace{\hat{f}(s, \xi)}_{|\hat{f}(s, \xi)| \leq \frac{C_N}{(1+|\xi|)^N}} ds.$$



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## Lemma [Maire, Comm. Partial Differential Equations, 1980]

Let  $O$  be an open set in  $\mathbb{R}^m$  and  $\Phi \in C^\omega(O)$ . For  $s \in O$  with  $\nabla\Phi(s) \neq 0$ , the solution  $\gamma_s : [0, \delta(s)) \rightarrow O$  of

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satisfies

$$\Phi(\gamma_s(\tau)) \geq \Phi(s) + C_0\tau^{\frac{1}{1-\theta}},$$

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## Proposition [Teissier, Acta Math., 1983]

Given a compact set  $\mathcal{H} \subset U$ , there exists  $C_1 \doteq C_1(\mathcal{H}) > 0$  such that, for every  $r \in B^\dagger(\mathcal{H})$ , any pair of points in a component of  $(B^\dagger)^{-1}(r) \cap \mathcal{H}$  can be joined by a real analytic path in  $(B^\dagger)^{-1}(r) \cap \mathcal{H}$  with length less than  $C_1$ .

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## Regarding the proof of (II) $\implies$ (I)

The approach will depend on  $b$ : if  $b$  is not exact, we consider a division of the pairs  $(t, \xi) \in \tilde{M} \times \mathbb{Z}^-$  in two classes.

The class (A) will consist of the pairs  $(t, \xi)$  for which there is  $\sigma \in D$  with  $b_\sigma < 0$  such that

$t$  and  $\sigma(t)$  are in the same component of  $\Omega_{\tilde{B}(t) + \frac{1}{1+|\xi|}}$ .

As for the pairs in the class (B), for each  $\sigma \in D$  with  $b_\sigma < 0$ ,

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## Lemma

For each pair  $(t, \xi)$  in the class (B), there is a piecewise smooth closed curve  $\gamma(t, \xi)$  in  $\tilde{M}$  based on  $t$  such that:

- $\gamma(t, \xi)$  is contained in  $\Omega_{\tilde{B}(t) + \frac{1}{1+|\xi|}}$  ;
- $|\gamma(t, \xi)| \leq C_0(1 + |\xi|)$  ;
- $\left| e^{i\xi \int_{\gamma(t, \xi)} a} - 1 \right| \geq \frac{K}{|\xi|^s}$  , for  $K > 0$ .

The hypothesis on the dimension is not required here as well.

A similar division and statement are true when  $b$  is exact.

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## Example 1

Assume that  $M$  is a closed manifold and  $b$  has only isolate singular points. The following statements are equivalent:

- (I)  $\mathbb{L}$  is globally solvable.
- (II) One of the two conditions below is satisfied:
  - The local primitives of  $b$  are open at any singular point.
  - The form  $b$  is exact, the semilevel sets  $\{t \in M : \tilde{B}(t) > r\}$  and  $\{t \in M : \tilde{B}(t) < r\}$  are connected for every  $r \in \mathbb{R}$ , and  $a$  is integral.

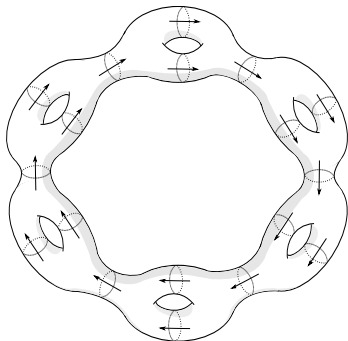
## Example 2

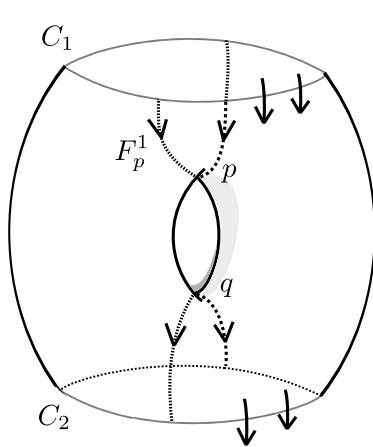
Assume that  $M$  is a closed manifold and  $\text{rank}(b) = 1$ . The following statements are equivalent:

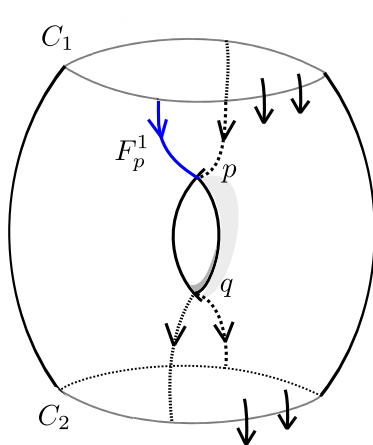
- (I)  $\mathbb{L}$  is globally solvable.
- (II)  $\mathcal{A} = \emptyset$ , or, for every  $\mathcal{O} \in \mathcal{A}$ ,  $I(\mathcal{O})$  is neither a rational nor a Liouville vector.

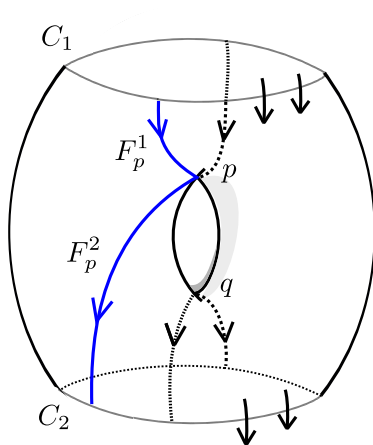
## Levitt's Theorem

Every Morse foliation on a surface of genus  $g > 1$  having only saddles as critical points (and not connected by leaves of the foliation), there are  $3g - 3$  pairwise disjoint cycles, transversal to the foliation, decomposing the surface into *pants*. There is only one saddle on each *pant*.

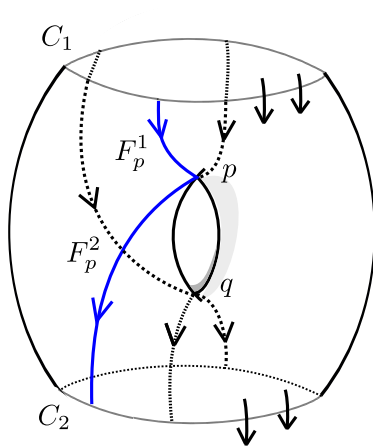


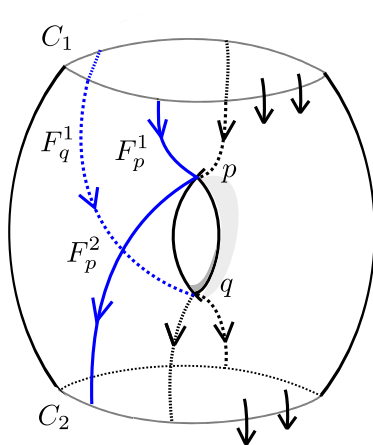


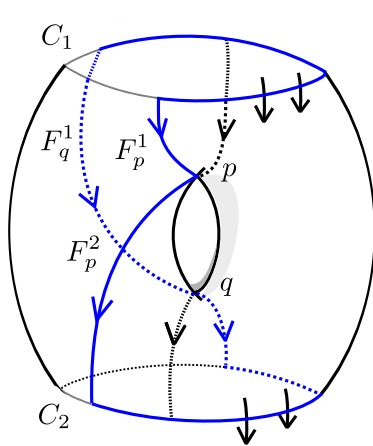












## Global solvability $\times$ Local solvability —Morse case

The operator  $\mathbb{L} = d_t + ib(t)\partial_x$  is said to be locally solvable at  $p = (t, x) \in M \times \mathbb{S}^1$  if any given neighborhood  $U$  of  $p$  contains another neighborhood  $V$  of  $p$  such that for every  $f \in C^\infty(U, \Lambda^{1,0})$  with  $\mathbb{L}f = 0$  there is  $u \in C^\infty(V)$  satisfying  $\mathbb{L}u = f$  on  $V$ .

Theorem [Treves, 1976]

The operator  $\mathbb{L}$  is locally solvable at  $(t_j, x)$  if and only if the index of the critical point  $t_j$  is not 1 neither  $n - 1$ .






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# References I

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